

数值实验:

Mar. 13 '91

回転球面上の2次元乱流

NO

1

基礎方程式

$$\frac{\partial \psi^*}{\partial t^*} + \frac{1}{a^*} J(\psi^*, \omega^*) + \frac{2\Omega^*}{a^{*2}} \frac{\partial \psi^*}{\partial \lambda} = \nu_2^* \Delta^* \omega^* - \nu_4^* \Delta^{*2} \omega^* \quad (1)$$

λ : 経度

μ : 半径縮度 ($\mu = \sin \phi$, ϕ : 緯度)

t^* : 時刻

$\psi^*(\lambda, \mu, t^*)$: 流函数

$$u^* = -\frac{\sqrt{1-\mu^2}}{a^*} \frac{\partial \psi^*}{\partial \mu}$$

$$v^* = \frac{1}{a^* \sqrt{1-\mu^2}} \frac{\partial \psi^*}{\partial \lambda}$$

$\omega^*(\lambda, \mu, t^*)$: 渦度 (r-成分)

$$\omega^* = \Delta^* \psi^*$$

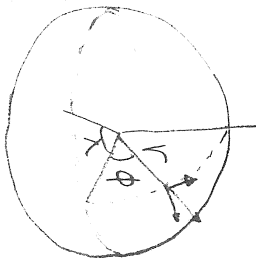
$$J(\alpha, \beta) = \frac{\partial \alpha}{\partial \lambda} \frac{\partial \beta}{\partial \mu} - \frac{\partial \alpha}{\partial \mu} \frac{\partial \beta}{\partial \lambda}$$

$$\Delta^* = \frac{1}{a^{*2}} \left[\frac{1}{1-\mu^2} \frac{\partial^2}{\partial \lambda^2} + \frac{\partial^2}{\partial \mu^2} \right] \left[(1-\mu^2) \frac{\partial}{\partial \mu} \right]$$

a^* : 惑星半径

Ω^* : 惑星自転角速度

球座標 (λ, ϕ, r)



$$\begin{pmatrix} x_1 = \lambda \\ x_2 = \phi \\ x_3 = r \end{pmatrix} \quad \begin{pmatrix} R_1 = r \cos \phi \\ R_2 = r \\ R_3 = \lambda \end{pmatrix}$$

	e_λ	e_ϕ	e_r
$\frac{\partial}{\partial \lambda}$	$e_\phi \sin \phi - e_r \cos \phi$	$-e_\lambda \sin \phi$	$e_\lambda \cos \phi$
$\frac{\partial}{\partial \phi}$	0	$-e_r$	e_ϕ
$\frac{\partial}{\partial r}$	0	0	0

$$\nabla = e_\lambda \frac{1}{r \cos \phi} \frac{\partial}{\partial \lambda} + e_\phi \frac{1}{r} \frac{\partial}{\partial \phi} + e_r \frac{\partial}{\partial r}$$

$$\text{grad } \Phi = e_\lambda \frac{1}{r \cos \phi} \frac{\partial \Phi}{\partial \lambda} + e_\phi \frac{1}{r} \frac{\partial \Phi}{\partial \phi} + e_r \frac{\partial \Phi}{\partial r}$$

$$\text{div } A = \frac{1}{r \cos \phi} \frac{\partial A_\lambda}{\partial \lambda} + \frac{1}{r \cos \phi} \frac{\partial}{\partial \phi} (\cos \phi A_\phi) + \frac{1}{r} \frac{\partial}{\partial r} (r A_r)$$

$$\begin{aligned} \text{rot } A = e_\lambda \left\{ \frac{1}{r} \left(\frac{\partial A_\phi}{\partial \lambda} - \frac{\partial}{\partial r} (r A_\lambda) \right) \right\} \\ + e_\phi \left\{ \frac{1}{r} \frac{\partial}{\partial r} (r A_\lambda) - \frac{1}{\cos \phi} \frac{\partial A_r}{\partial \lambda} \right\} \\ + e_r \left\{ \frac{1}{r \cos \phi} \left(\frac{\partial A_\phi}{\partial \lambda} - \frac{\partial}{\partial \phi} (\cos \phi A_\lambda) \right) \right\} \end{aligned}$$

$$\Delta \Phi = \frac{1}{r^2 \cos \phi} \frac{\partial^2 \Phi}{\partial \lambda^2} + \frac{1}{r^2 \cos \phi} \frac{\partial}{\partial \phi} (\cos \phi \frac{\partial \Phi}{\partial \phi}) + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial \Phi}{\partial r})$$

球面2nd積分

$$\begin{aligned} \int dS &= \int_0^{2\pi} d\lambda \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} d\phi \, a^2 \cos\phi \\ &= \int_0^{2\pi} d\lambda \int_{-1}^1 dy \, a^2 \end{aligned}$$

部分積分 (A, B は球面上の smooth な関数)

$$\begin{aligned} \int A \Delta B \, dS &= - \int \text{grad } A \cdot \text{grad } B \, dS \\ &= \int (\Delta A) B \, dS \end{aligned}$$

$$\int A \frac{\partial B}{\partial \lambda} \, dS = - \int \frac{\partial A}{\partial \lambda} B \, dS$$

Jacobian の積分

$$\begin{aligned} \int \frac{1}{\cos\phi} \frac{\partial(A, B)}{\partial(\lambda, \phi)} \, dS &= \int \frac{\partial(A, B)}{\partial(\lambda, \mu)} \, dS \\ &= 0 \end{aligned}$$

$$\begin{aligned} \operatorname{div} A &= \frac{1}{r^2 \cos \phi} \left\{ \frac{\partial}{\partial \lambda} (r A_\lambda) + \frac{\partial}{\partial \phi} (r \cos \phi A_\phi) \right. \\ &\quad \left. + \frac{\partial}{\partial r} (r^2 \cos \phi A_r) \right\} \\ &= \frac{1}{r \cos \phi} \frac{\partial A_\lambda}{\partial \lambda} + \frac{1}{r \cos \phi} \frac{\partial}{\partial \phi} (\cos \phi A_\phi) \\ &\quad + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) \end{aligned} //$$

$$\operatorname{rot} A = \frac{1}{r^2 \cos \phi} \begin{vmatrix} r \cos \phi e_\lambda & r e_\phi & e_r \\ \frac{\partial}{\partial \lambda} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial r} \\ r \cos \phi A_\lambda & r A_\phi & A_r \end{vmatrix}$$

$$\begin{aligned} &= e_\lambda \frac{1}{r \cos \phi} \left\{ \frac{\partial A_r}{\partial \phi} - \frac{\partial}{\partial r} (r A_\phi) \right\} \\ &\quad + e_\phi \frac{1}{r \cos \phi} \left\{ \frac{\partial}{\partial r} (r \cos \phi A_\lambda) - \frac{\partial A_r}{\partial \lambda} \right\} \\ &\quad + e_r \frac{1}{r^2 \cos \phi} \left\{ \frac{\partial}{\partial \lambda} (r A_\phi) - \frac{\partial}{\partial \phi} (r \cos \phi A_\lambda) \right\} \\ &= e_\lambda \frac{1}{r} \left\{ \frac{\partial A_r}{\partial \phi} - \frac{\partial}{\partial r} (r A_\phi) \right\} \\ &\quad + e_\phi \frac{1}{r} \left\{ \frac{\partial}{\partial r} (r A_\lambda) - \frac{1}{\cos \phi} \frac{\partial A_r}{\partial \lambda} \right\} \\ &\quad + e_r \frac{1}{r \cos \phi} \left\{ \frac{\partial A_\phi}{\partial \lambda} - \frac{\partial}{\partial \phi} (\cos \phi A_\lambda) \right\} // \end{aligned}$$

$$\Delta \Phi = \nabla \cdot \nabla \Phi$$

$$\begin{aligned} &= \frac{1}{r^2 \cos \phi} \left\{ \frac{\partial}{\partial \lambda} \left(\frac{1}{r \cos \phi} \frac{\partial \Phi}{\partial \lambda} \right) \right. \\ &\quad \left. + \frac{\partial}{\partial \phi} \left(\frac{1}{r} \frac{\partial \Phi}{\partial \phi} \right) \right. \\ &\quad \left. + \frac{\partial}{\partial r} \left(\frac{r^2 \cos \phi}{1} \frac{\partial \Phi}{\partial r} \right) \right\} \\ &= \frac{1}{r^2 \cos \phi} \frac{\partial^2 \Phi}{\partial \lambda^2} + \frac{1}{r^2 \cos \phi} \frac{\partial}{\partial \phi} \left(\cos \phi \frac{\partial \Phi}{\partial \phi} \right) \\ &\quad + \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \Phi}{\partial r} \right) // \end{aligned}$$

U_2^* , U_4^* : 粘性 (超粘性) 系数

$$u^* = E_r \times \text{grad } \varphi^*$$

$$= \begin{vmatrix} E_r & E_\phi & -E_r \\ 0 & 0 & 1 \\ \frac{1}{a^* \cos \phi} \frac{\partial \varphi^*}{\partial \lambda} & \frac{1}{a^*} \frac{\partial \varphi^*}{\partial \phi} & \frac{\partial \varphi^*}{\partial r} \end{vmatrix}$$

$$\frac{dH}{d\phi} = \frac{d}{d\phi} \sin \phi = \cos \phi$$

$$= -\frac{1}{a^*} \frac{\partial \varphi^*}{\partial \phi} E_r + \frac{1}{a^* \cos \phi} \frac{\partial \varphi^*}{\partial \lambda} E_\phi$$

$$= -\frac{\sqrt{1-\mu^2}}{a^*} \frac{\partial \varphi^*}{\partial \mu} E_r + \frac{1}{a^* \sqrt{1-\mu^2}} \frac{\partial \varphi^*}{\partial \lambda} E_\phi$$

$$\omega^* = E_r \cdot \text{rot } u$$

$$= \frac{1}{a^* \cos \phi} \left\{ \frac{\partial v^*}{\partial \lambda} - \frac{\partial \phi}{\partial \phi} (\cos \phi u^*) \right\}$$

$$= \frac{1}{a^* \sqrt{1-\mu^2}} \left\{ a^* \frac{\partial^2 \varphi^*}{\partial \lambda^2} + \sqrt{1-\mu^2} \frac{\partial}{\partial \mu} \left(\frac{1-\mu^2}{a^*} \frac{\partial \varphi^*}{\partial \mu} \right) \right\}$$

$$= \frac{1}{a^{*2}} \left[\frac{1}{1-\mu^2} \frac{\partial^2 \varphi^*}{\partial \lambda^2} + \frac{\partial}{\partial \mu} \left\{ (1-\mu^2) \frac{\partial \varphi^*}{\partial \mu} \right\} \right]$$

$$= \Delta^* \varphi^* //$$

(1) \rightarrow

$$\frac{\partial}{\partial t^*} \Delta^* \varphi^* + \frac{1}{a^{*2}} \mathcal{J}(\varphi^*, \Delta^* \varphi^*) + \frac{2\Omega^*}{a^{*2}} \frac{\partial \varphi^*}{\partial \lambda}$$

$$= U_2^* \Delta^{*2} \varphi^* - U_4^* \Delta^{*3} \varphi^* \quad (2)$$

無次元化.

$$t^* = T t,$$

t : 無次元時刻

$$\psi^* = \frac{L^2}{q^{*2}} \psi,$$

ψ : 無次元流れ関数

$$\Delta^* = \frac{1}{q^{*2}} \Delta,$$

Δ : 無次元ラプラスアン

T : 時間の尺度

L : 距離の尺度

$$\Delta = \frac{1}{1-\mu^2} \frac{\partial^2}{\partial x^2} + \frac{\partial}{\partial y} \left\{ (1-\mu^2) \frac{\partial}{\partial y} \right\}$$

$$\omega^* = \Delta^* \psi^* = \frac{1}{q^{*2}} \cdot \frac{L^2}{T} \Delta \psi$$

$$(2) \rightarrow \frac{L^2}{q^{*2} T^2} \frac{\partial^2}{\partial t^2} \Delta \psi + \frac{L^4}{q^{*4} T^2} J(\psi, \Delta \psi) + \frac{2L^2 \Omega^*}{q^{*2} T} \frac{\partial \psi}{\partial t}$$

$$= \frac{U_3^* L^2}{q^{*4} T} \Delta^2 \psi - \frac{U_4^* L^2}{q^{*6} T} \Delta^3 \psi$$

$$\therefore \frac{\partial^2}{\partial t^2} \Delta \psi + \frac{L^2}{q^{*2}} J(\psi, \Delta \psi) + 2\Omega^* T \frac{\partial \psi}{\partial t}$$

$$= \frac{U_3^* T}{q^{*2}} \Delta^2 \psi - \frac{U_4^* T}{q^{*4}} \Delta^3 \psi$$

$$\frac{\partial}{\partial t} \Delta \psi + \nu^2 \nabla^2 (\psi, \Delta \psi) + 2.02 \frac{\partial \psi}{\partial x} = \nu_2 \Delta^2 \psi - \nu_4 \Delta^3 \psi \quad (3)$$

$$\Omega^* = \frac{1}{L_0} \Omega \quad \Omega: \text{無次元 自転角速度}$$

$$\nu_2^* = \frac{\alpha^{*2}}{\tau} \nu_2 = \frac{\alpha^{*2} \nu}{L_0^3} \nu_2 \quad \nu_2: \text{無次元 粘性係数}$$

$$\nu_4^* = \frac{\alpha^{*4}}{\tau} \nu_4 = \frac{\alpha^{*4} \nu}{L_0^3} \nu_4 \quad \nu_4: \text{無次元 超粘性係数}$$

$$\nu^2 = \frac{L^2}{\alpha^{*2}} \quad \nu: \text{距離 } \alpha \text{ 尺度の惑星半径 } \alpha \text{ 比}$$

$$0 < \nu \leq 2\pi$$

$$L_{max} = 2\pi \alpha^*$$

$$2\Omega = 2T\Omega^* = \frac{25\Omega^* L}{U} = R_0^{-1} \quad (\text{ロビン-数})$$

$$(U = L/T)$$

無次元パラメータ: ν^2 , 25Ω , ν_2 , ν_4 かけ回-2-
 あるいは, 運動は力学的に相似になる。

- $\nu^2 = 1 \quad L = \alpha^* \text{ 程度}$

- 初期値 $\psi(0) = 1, \quad \dot{\psi} = 0 \quad \Omega: \text{実験パラメータ}$

- $\nu_2 = 0, \quad \nu_4 = \text{const.}$

- 81.0 初期値 $\alpha^{*2} \nu^2$

81.0 ν_4

L_0 単位

dissipation number

運動エネルギーとエンタルピー

単位面積あたりの平均運動エネルギー

$$\begin{aligned}
 \bar{\epsilon}^*(ct) &= \frac{1}{4\pi a^* x^2} \int_0^{2\pi} \int_{-1}^1 \frac{1}{2} (u^{*2} + v^{*2}) a^{*2} du dv \\
 &= \frac{1}{4\pi} \int_0^{2\pi} \int_{-1}^1 \frac{1}{2} (u^{*2} + v^{*2}) du dv \quad [m^2 s^{-2}] \\
 &= \frac{1}{4\pi} \int_0^{2\pi} \int_{-1}^1 \frac{1}{2 a^{*2}} \left\{ (1-\mu^2) \left(\frac{\partial \psi^*}{\partial \mu} \right)^2 + \frac{1}{1-\mu^2} \left(\frac{\partial \psi^*}{\partial \lambda} \right)^2 \right\} du dv \\
 &= \frac{1}{8\pi a^{*2}} \int_0^{2\pi} \int_{-1}^1 \left[(1-\mu^2)^2 \psi^* \frac{\partial \psi^*}{\partial \mu} \right]_{-1}^1 - \int_{-1}^1 \psi^* \frac{\partial}{\partial \mu} \left\{ (1-\mu^2) \frac{\partial \psi^*}{\partial \mu} \right\} du \left[d\lambda \right] \\
 &\quad + \frac{1}{8\pi a^{*2}} \int_{-1}^1 \left[\frac{1}{1-\mu^2} \psi^* \frac{\partial \psi^*}{\partial \lambda} \right]_{\lambda=0}^{2\pi} - \int_0^{2\pi} \frac{1}{1-\mu^2} \psi^* \left[\frac{\partial \psi^*}{\partial \lambda} d\lambda \right] du \\
 &= \frac{1}{8\pi a^{*2}} \int_0^{2\pi} \int_{-1}^1 \psi^* \left[\frac{1}{1-\mu^2} \frac{\partial^2 \psi^*}{\partial \lambda^2} + \frac{\partial}{\partial \mu} \left\{ (1-\mu^2) \frac{\partial \psi^*}{\partial \mu} \right\} \right] du d\lambda \\
 &= \frac{1}{8\pi} \int_0^{2\pi} \int_{-1}^1 \psi^* \Delta^* \psi^* du d\lambda \\
 &\quad (\text{変数変換、無次元化}) \\
 &= \frac{1}{8\pi} \int_0^{2\pi} \int_{-1}^1 \frac{L^4}{T^2 a^{*2}} \int_0^{2\pi} \int_{-1}^1 \psi \Delta \psi du d\lambda \\
 &= \frac{1}{8\pi} \cdot \boxed{U^2 \rho^2} \int_0^{2\pi} \int_{-1}^1 \psi \Delta \psi du d\lambda
 \end{aligned}$$

正規化ノボシハル関数

$$\Sigma^*(t) = -\frac{U^2 \nu^2}{2} \frac{1}{4\pi} \int_{\Omega} \sum_{l=1}^{2l} \sum_{m=0}^l \sum_{m'=-l}^l \psi_n^m \tilde{Y}_n^{m'} \times \sum_{m''=0}^{2l} \sum_{m'''=-l}^{l'} -n'(n'+1) \psi_{n'}^{m''} \tilde{Y}_{n'}^{m'''} d\Omega_{n'}$$

(Note: E-3)

$$\downarrow \\ = \frac{U^2 \nu^2}{2} \sum_n \sum_{m_l} n(n+1) |\psi_n^m(t)|^2$$

正規化ノボシハル関数: $E^*(n, t)$

$$E^*(n, t) \equiv \frac{U^2 \nu^2}{2} \sum_{m=-l}^l n(n+1) |\psi_n^m(t)|^2$$

$$\Sigma^*(t) = \sum_{n=0}^{\infty} E^*(n, t)$$

無次元化

$$\Sigma^*(t) = U^2 \nu^2 \Sigma(t)$$

$$E^*(n, t) = U^2 \nu^2 E(n, t)$$

但し,

$$\Sigma(t) = \frac{1}{2} \sum_{l=0}^{\infty} \sum_{m=-l}^l n(n+1) |\psi_n^m(t)|^2$$

$$E(n, t) = \frac{1}{2} \sum_{m=-l}^l n(n+1) |\psi_n^m(t)|^2$$

$$\left(\Sigma(t) = \sum_{n=0}^{\infty} E(n, t) \right)$$

単位面積 板の平均インデックス

$$\begin{aligned}
 Q^*(t) &= \frac{1}{4\pi a^{*2}} \int_0^{2\pi} \int_{-1}^1 \frac{1}{2} (\Delta^* \psi^*)^2 a^{*2} du dv \\
 &= \frac{1}{4\pi} \int_0^{2\pi} \int_{-1}^1 \frac{1}{2} (\Delta^* \psi^*)^2 du dv \quad [5-27] \\
 &\quad (\text{変数の無次元化}) \\
 &= \frac{1}{8\pi} \frac{L^4}{a^{*4} T^2} \int_0^{2\pi} \int_{-1}^1 (\Delta \psi)^2 du dv \\
 &= \frac{1}{8\pi} \frac{1}{T^2} \rho^4 \int_0^{2\pi} \int_{-1}^1 (\Delta \psi)^2 du dv
 \end{aligned}$$

インデックス-2N°シムル関数

$$Q^*(t) = \frac{\rho^4}{2T^2} \sum_n \sum_m n^2 (n+1)^2 |\psi_n^m(t)|^2$$

インデックス-2N°シムル関数: $Q^*(n, t)$

$$Q^*(n, t) \equiv \frac{\rho^4}{2T^2} \sum_{m=-n}^n n^2 (n+1)^2 |\psi_n^m(t)|^2$$

$$Q^*(t) = \sum_{n=0}^N Q^*(n, t)$$

無次元化

$$Q^*(t) = \frac{y_{11}}{y_{12}} Q(t)$$

$$Q^*(n, t) = \frac{y_{11}}{y_{12}} Q(n, t)$$

但し,

$$Q(t) = \frac{1}{2} \sum_{n=0}^{\infty} \sum_{m=-n}^n n^2 (n+1)^2 |Q_n^m(t)|^2$$

$$Q(n, t) = \frac{1}{2} \sum_{m=-n}^n n^2 (n+1)^2 |Q_n^m(t)|^2$$

$$\left(Q(t) = \sum_{n=0}^{\infty} Q(n, t) \right)$$

初期値

工礼 β^n -RANSTL素数の演算型に固定格。

$$E(0) = \sum_{n=0}^M E(n, 0) = 1$$

$n=1$: 剛体回転成分はゼロと可。

$$E(n, 0) = \alpha n^j e^{-\beta n}$$

実解LIT, j, β 未知, $E(0) = 1$ と可 α 未知。

G/NIT

j, β 未知

$$\sum_{n=0}^M n^j e^{-\beta n} \quad \alpha \text{ 計算}$$

$$\alpha = 1 / \sum_{n=0}^M n^j e^{-\beta n}$$

試数- markov分配 (位相試数) $\rightarrow Q_n(0)$

$$Q(n, 0), \quad Q(0)$$

$$(j=5, \beta=0.5)$$

$$U_0 = \sqrt{E(0)} \quad E(0) = 1, \quad Q(0) = 180.$$

$$L_0 = \sqrt{E(0) / Q(0)}$$

$$U_0 = 1$$

$$T_0 = L_0 / U_0$$

$$L_0 = 0.0745$$

$$T_0$$

output

例 初相位：空间对称性

$$\varphi^I(\lambda, \mu, 0) = \varphi(\lambda, \mu) = -\varphi^V(\lambda, \mu, 0)$$

$$\varphi^I(\lambda, \mu, 0) = \varphi(-\lambda, \mu) = -\varphi^{II}(\lambda, \mu, 0)$$

$$\varphi^{III}(\lambda, \mu, 0) = \varphi(\lambda, -\mu) = -\varphi^{III}(\lambda, \mu, 0)$$

$$\varphi^{IV}(\lambda, \mu, 0) = \varphi(-\lambda, -\mu) = -\varphi^{IV}(\lambda, \mu, 0)$$

$Z^3 = 8$ cases.

II. IV:

$$\varphi^I = \varphi(-\lambda, \mu)$$

$$= \sum_{n=0}^{\infty} \sum_{m=-n}^n \varphi_n^m \tilde{Y}_n^m(-\lambda, \mu)$$

$$= \sum_n \sum_m \varphi_n^m \tilde{P}_n^m(\mu) e^{-im\lambda}$$

$$= \sum_n \sum_{m'} \varphi_n^{-m'} \tilde{P}_n^{-m'}(\mu) e^{im'\lambda}$$

$m' = -m$

$$= \sum_n \sum_{m'} \varphi_n^{-m'} (-1)^{m'} \tilde{P}_n^{m'} e^{im'\lambda}$$

$m = m'$

$$= \sum_n \sum_{m'} (-1)^{m'} \varphi_n^{-m'} \tilde{Y}_n^{m'}(\lambda, \mu)$$

$$= \sum_n \sum_{m'} (\varphi_n^m)^* \tilde{Y}_n^m$$

$$\therefore \varphi_n^m = (\varphi_n^m)^*$$

$$\varphi_n^m = -(\varphi_n^m)^*$$

III. III

$$\begin{aligned}
 \varphi_{III} &= \varphi(\lambda, -\mu) \\
 &= \sum_{n=0}^{\infty} \sum_{m=-n}^n \varphi_n^m \tilde{Y}_n^m(\lambda, -\mu) \\
 &= \sum_n \sum_m \varphi_n^m (-1)^{n+m} \tilde{Y}_n^m(\lambda, \mu)
 \end{aligned}$$

$$\therefore \varphi_{III}^m = (-1)^{n+m} \varphi_{III}^m$$

$$\varphi_{III}^m = (-1)^{n+m+1} \varphi_{III}^m$$

IV. III

$$\varphi_{IV} = \varphi(-\lambda, -\mu)$$

$$= \sum_{n=0}^{\infty} \sum_{m=-n}^n \varphi_n^m \tilde{Y}_n^m(-\lambda, -\mu)$$

$$= \sum_m \sum_{n=-m}^m \varphi_n^m (-1)^{n+m} \tilde{Y}_n^m(-\lambda, \mu)$$

$$= \sum_n \sum_{m'} (-1)^{n+m'} \varphi_n^{m'} \tilde{P}_n^{m'}(\mu) e^{-im'\lambda}$$

$$= \sum_{n, m'} (-1)^{n-m'} \varphi_n^{-m'} (-1)^{m'} \tilde{P}_n^{m'}(\mu) e^{im'\lambda}$$

$$= \sum_n \sum_m (-1)^{n-m} (-1)^m \varphi_n^{-m} \tilde{Y}_n^m(\lambda, \mu)$$

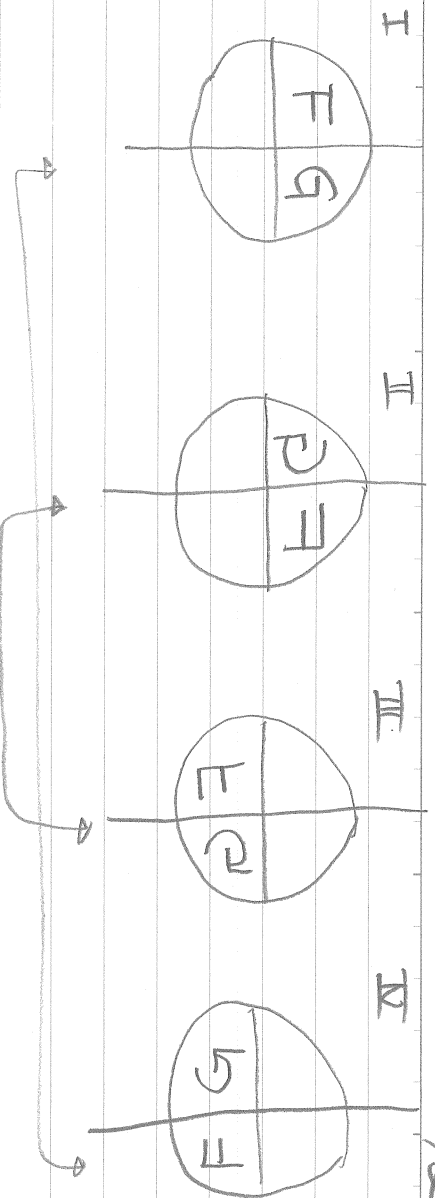
$$= \sum_n \sum_m (-1)^{n-m} (\varphi_n^m)^* \tilde{Y}_n^m(\lambda, \mu)$$

$$\therefore \varphi_{IV}^m = (-1)^{n-m} (\varphi_{III}^m)^*$$

$$\varphi_{III}^m = (-1)^{n-m+1} (\varphi_{IV}^m)^*$$

NO.

12



12 L, $\Omega \rightarrow -\Omega$

<<< INITIAL STATE >>>

J =01 A = 0.13022E-03
TOTAL ENERGY = 0.10000E+01
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.74533E-01

B = 0.50

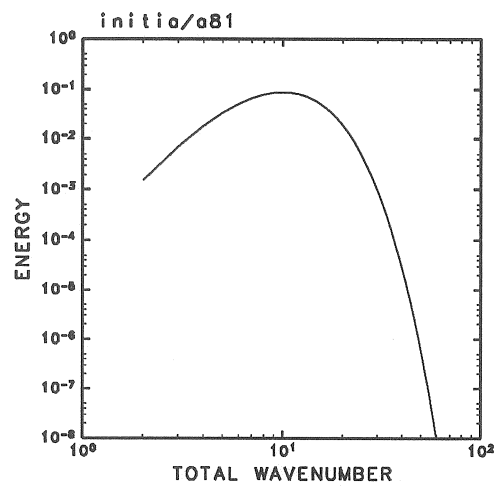
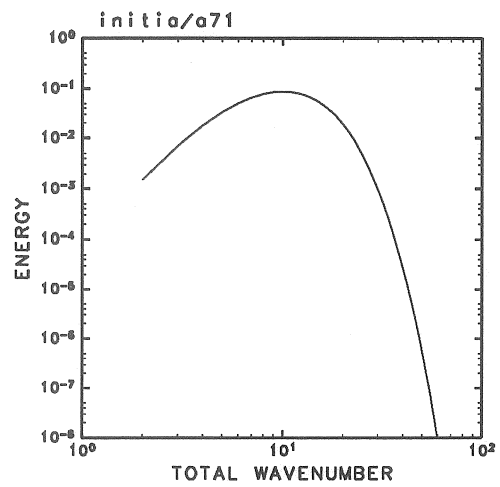
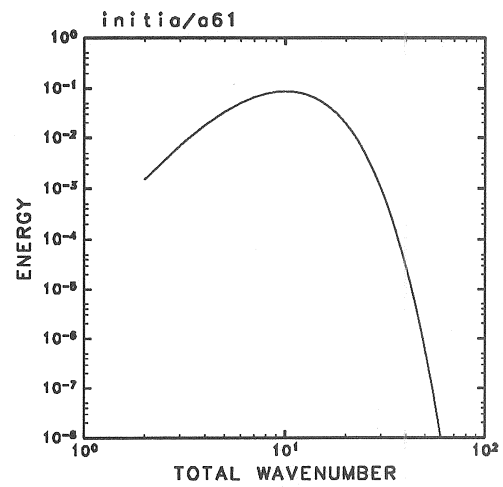
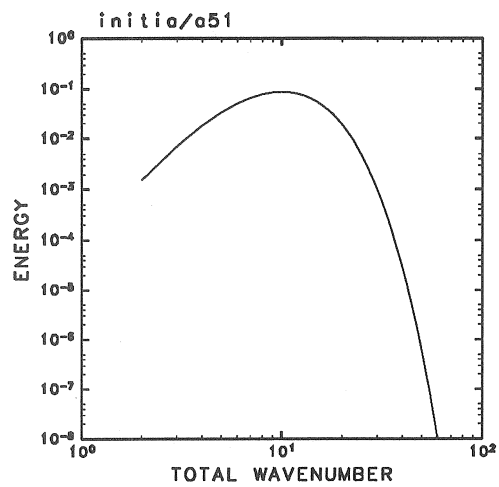
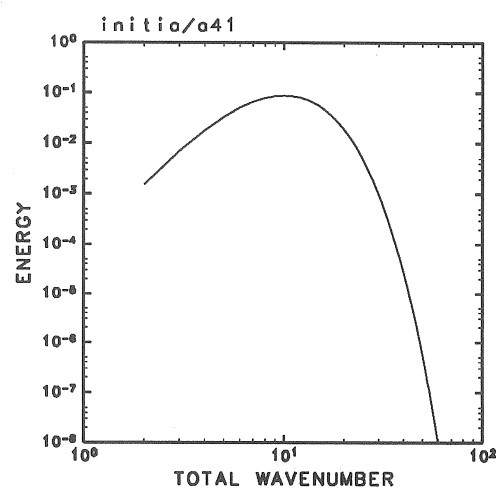
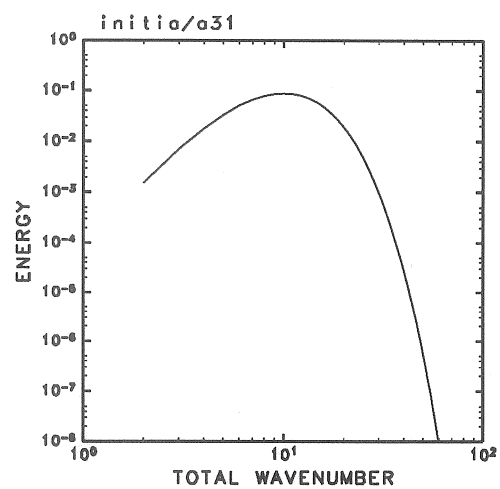
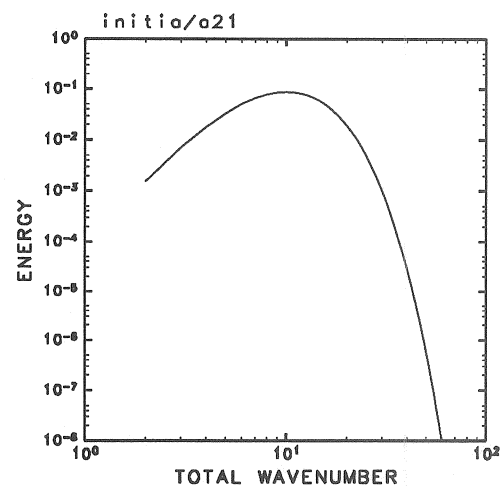
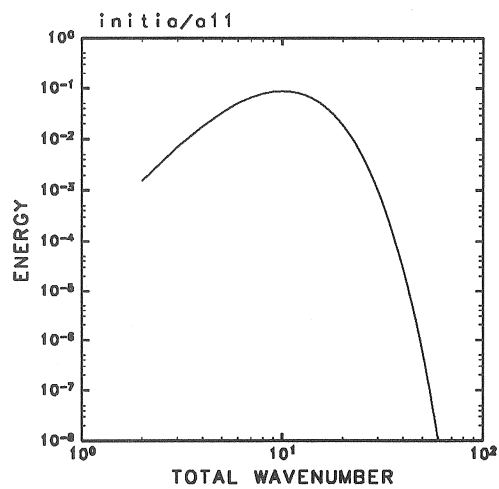
TOTAL ENSTROPHY = 0.18001E+03

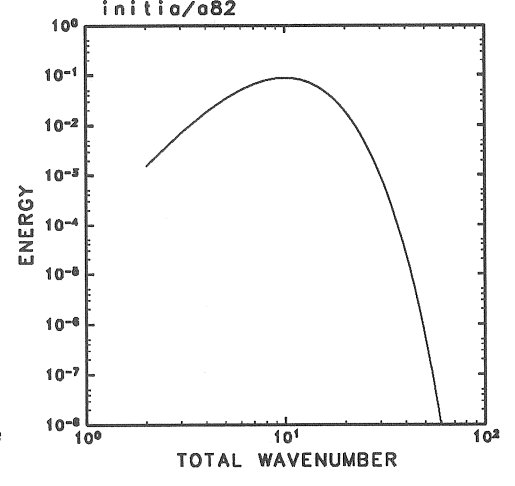
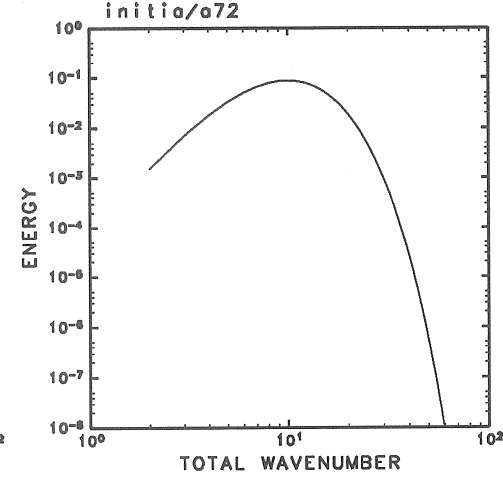
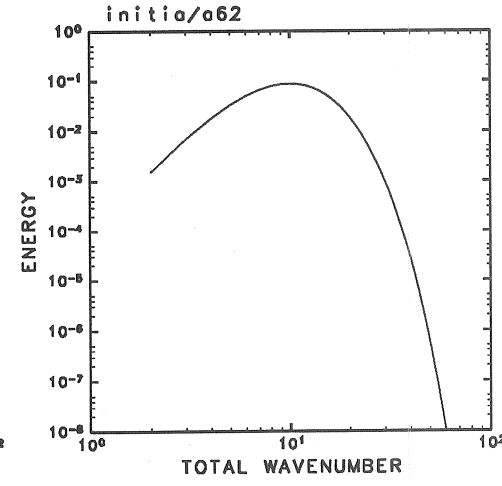
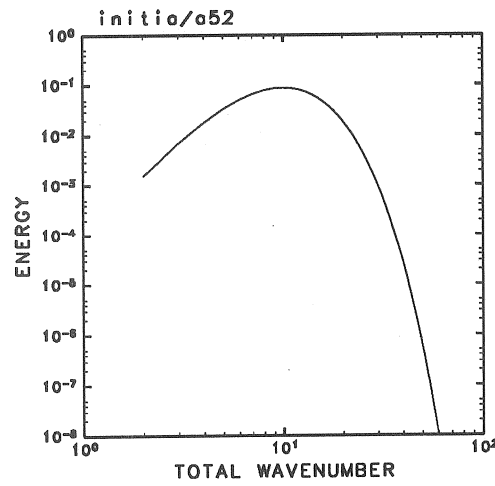
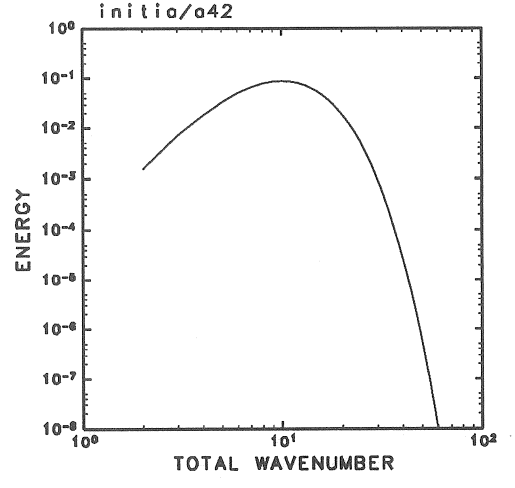
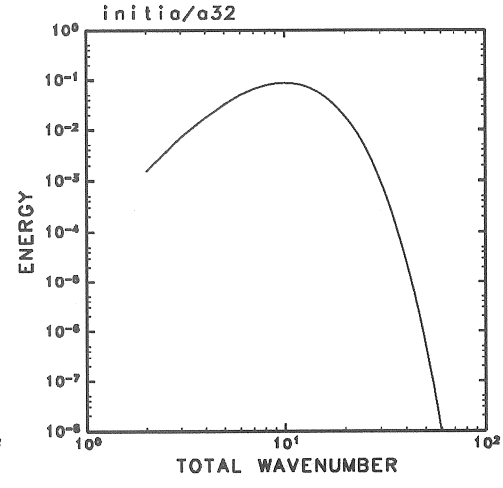
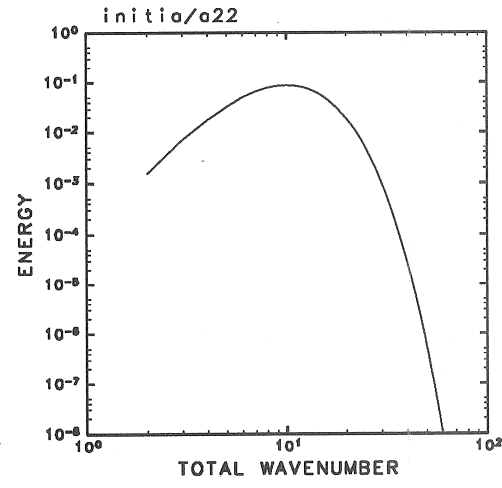
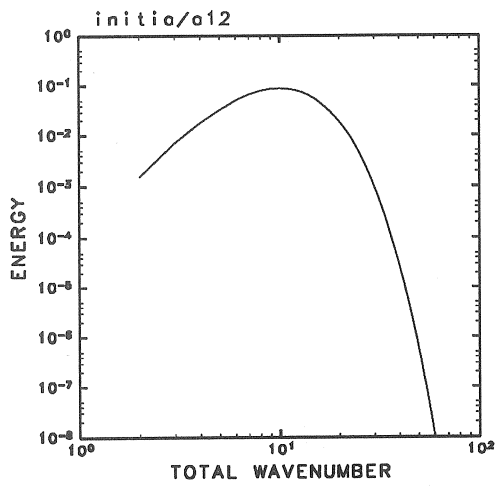
<<< INITIAL STATE >>>

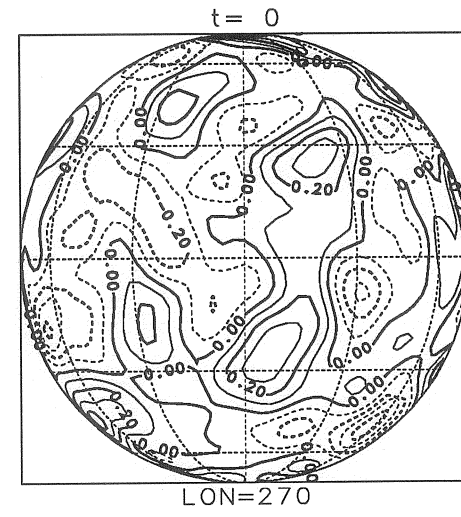
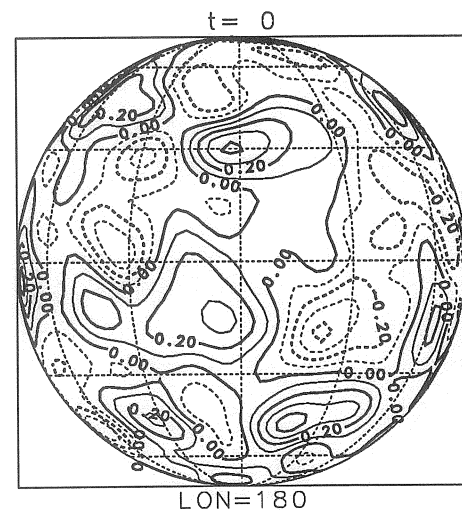
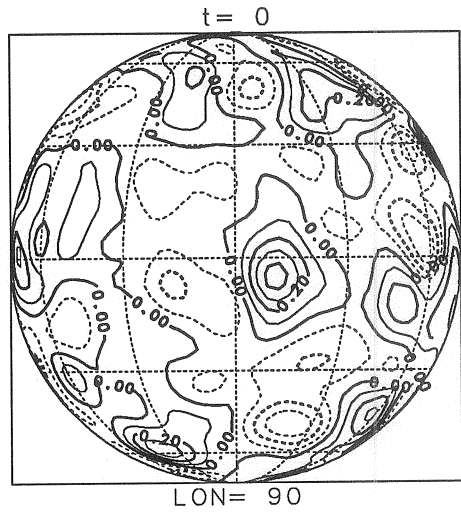
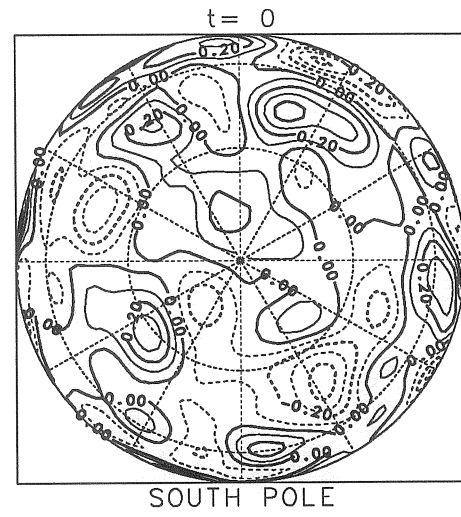
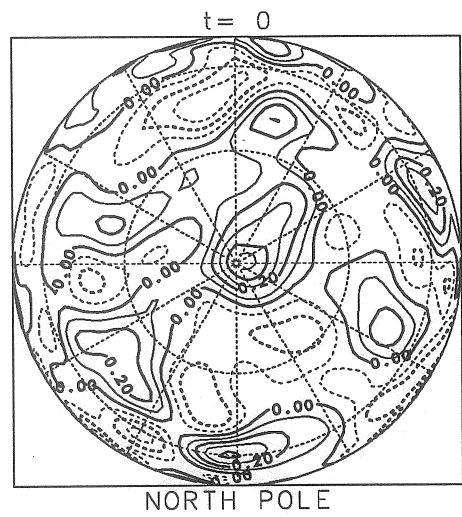
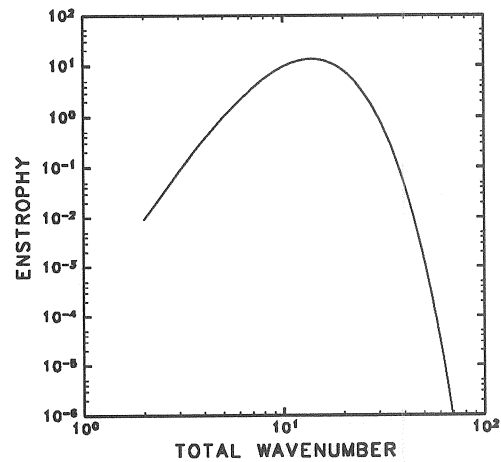
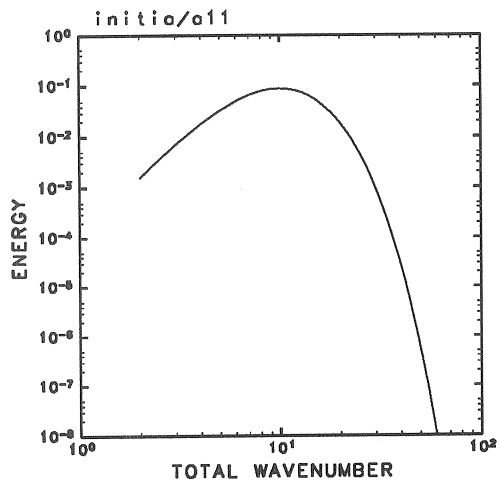
J =02 A = 0.13022E-03
TOTAL ENERGY = 0.10000E+01
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.74533E-01

B = 0.50

TOTAL ENSTROPHY = 0.18001E+03







initia/a11



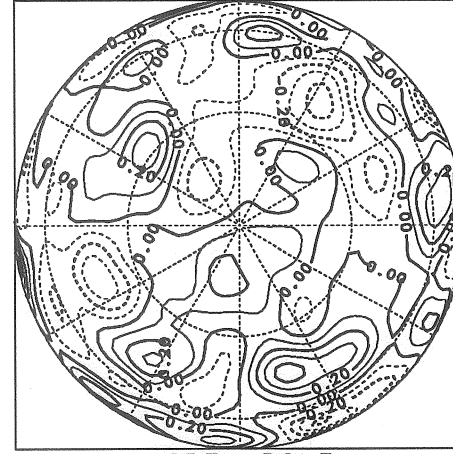
NORTH POLE

initia/a21



NORTH POLE

initia/a31



NORTH POLE

initia/a41



NORTH POLE

initia/a51



NORTH POLE

initia/a61



NORTH POLE

initia/a71



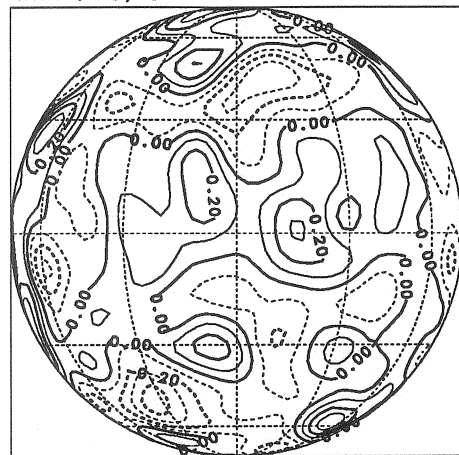
NORTH POLE

initia/a81



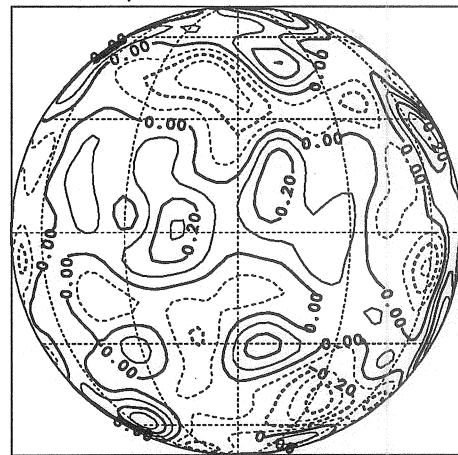
NORTH POLE

initia/a11



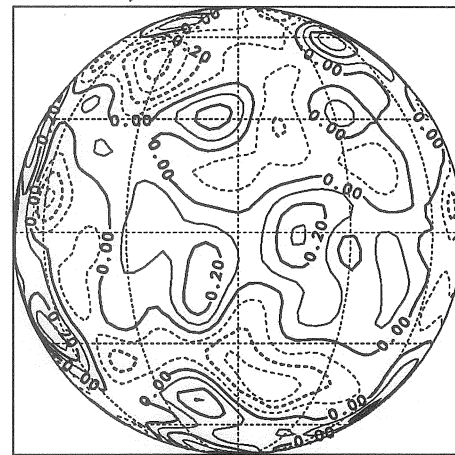
LON= 0

initia/a21



LON= 0

initia/a31



LON= 0

initia/a41



LON= 0

initia/a51



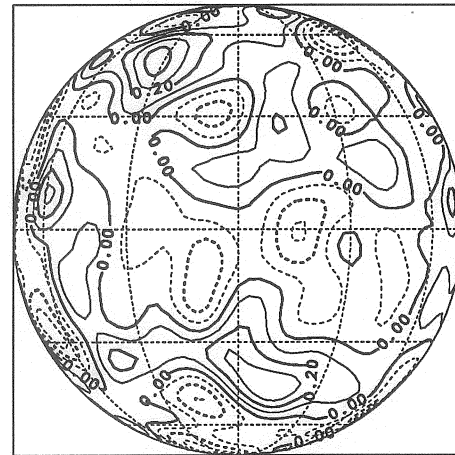
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initia/a61



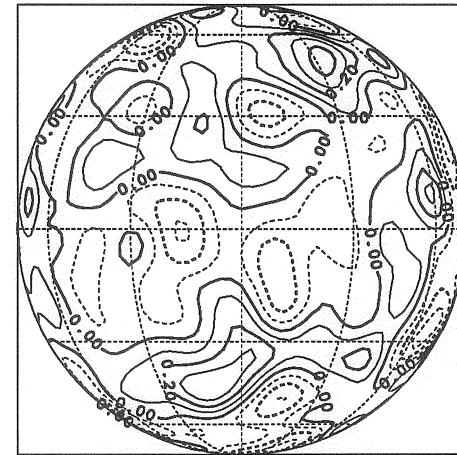
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initia/a71



LON= 0

initia/a81



LON= 0

initia/a12



LON= 0

initia/a22



LON= 0

initia/a32



LON= 0

initia/a42



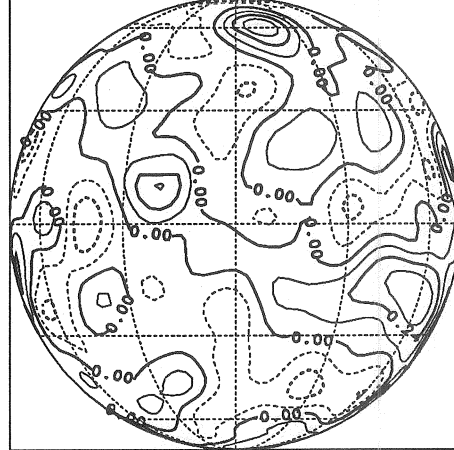
LON= 0

initia/a52



LON= 0

initia/a62



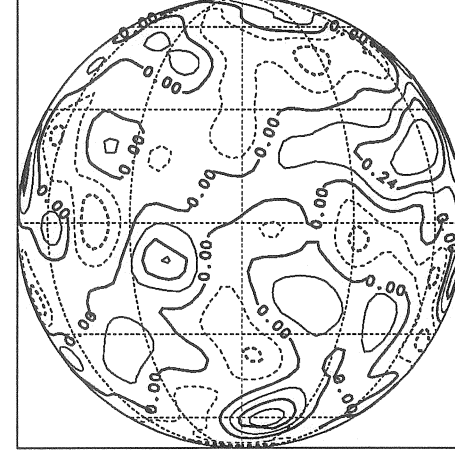
LON= 0

initia/a72



LON= 0

initia/a82



LON= 0

对账单

JIMAX5

I

0

250

500

750

1000

AZ001	A11	1.000000	0.899270	0.869710	0.855300	0.846260	—
AZ001	A21	1.000000	0.898020	0.869120	0.855460	0.845210	。
AZ001	A31	1.000000	0.898020	0.869120	0.855460	0.845210	。
AZ001	A41	1.000000	0.899270	0.869710	0.855300	0.846260	—
AZ001	A51	1.000000	0.898020	0.869120	0.855460	0.845210	。
AZ001	A61	1.000000	0.899270	0.869710	0.855300	0.846260	—
AZ001	A71	1.000000	0.899270	0.869710	0.855300	0.846260	—
AZ001	A81	1.000000	0.898020	0.869120	0.855460	0.845210	。

AZ002	A11	1.000000	0.901370	0.867110	0.852380	0.844350	—
AZ002	A21	1.000000	0.898410	0.867120	0.852870	0.845200	。
AZ002	A31	1.000000	0.900340	0.868870	0.853660	0.845380	。
AZ002	A41	1.000000	0.901680	0.872670	0.858180	0.848810	。
AZ002	A51	1.000000	0.900340	0.868870	0.853660	0.845380	。
AZ002	A61	1.000000	0.901680	0.872670	0.858180	0.848810	。
AZ002	A71	1.000000	0.901370	0.867110	0.852380	0.844350	。
AZ002	A81	1.000000	0.898410	0.867120	0.852870	0.845200	。

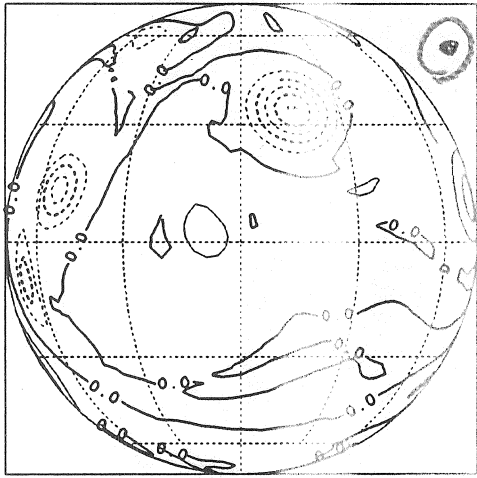
AZ003	A11	1.000000	0.899820	0.869470	0.855910	0.847080	—
AZ003	A21	1.000000	0.899040	0.867980	0.851510	0.842060	X
AZ003	A31	1.000000	0.899880	0.869000	0.854590	0.845670	。
AZ003	A41	1.000000	0.901120	0.874330	0.859310	0.849020	。
AZ003	A51	1.000000	0.899880	0.869000	0.854590	0.845670	。
AZ003	A61	1.000000	0.901120	0.874330	0.859310	0.849020	。
AZ003	A71	1.000000	0.899820	0.869470	0.855910	0.847080	。
AZ003	A81	1.000000	0.899040	0.867980	0.851510	0.842060	X

AZ004	A11	1.000000	0.899840	0.867800	0.851680	0.839430	
AZ004	A21	1.000000	0.900150	0.863840	0.844970	0.833080	
AZ004	A31	1.000000	0.901970	0.865580	0.845570	0.832010	
AZ004	A41	1.000000	0.901600	0.868530	0.848960	0.834510	
AZ004	A51	1.000000	0.901970	0.865580	0.845570	0.832010	
AZ004	A61	1.000000	0.901600	0.868530	0.848960	0.834510	
AZ004	A71	1.000000	0.899840	0.867800	0.851680	0.839430	
AZ004	A81	1.000000	0.900150	0.863840	0.844970	0.833080	

AZ005	A11	1.000000	0.898240	0.857630	0.833970	0.819320	
AZ005	A21	1.000000	0.900210	0.860520	0.835750	0.818000	
AZ005	A31	1.000000	0.902520	0.857910	0.833210	0.816570	
AZ005	A41	1.000000	0.901580	0.857130	0.830190	0.813750	
AZ005	A51	1.000000	0.902520	0.857910	0.833210	0.816570	
AZ005	A61	1.000000	0.901580	0.857130	0.830190	0.813750	
AZ005	A71	1.000000	0.898240	0.857630	0.833970	0.819320	
AZ005	A81	1.000000	0.900210	0.860520	0.835750	0.818000	

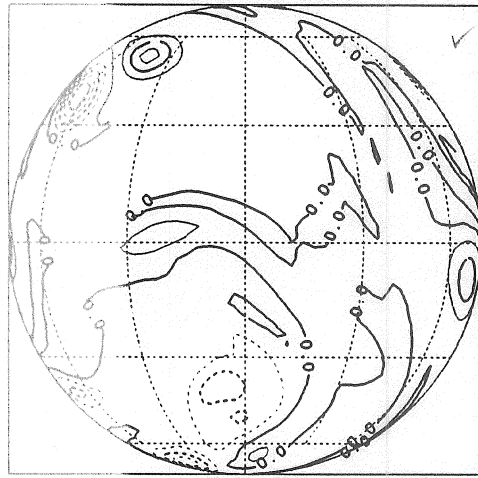
AZ006	A11	1.000000	0.886690	0.830720	0.798710	0.777760	
AZ006	A21	1.000000	0.888130	0.834880	0.798510	0.774810	
AZ006	A31	1.000000	0.887070	0.832040	0.797280	0.771840	
AZ006	A41	1.000000	0.887660	0.830400	0.794730	0.768630	
AZ006	A51	1.000000	0.887070	0.832040	0.797280	0.771840	
AZ006	A61	1.000000	0.887660	0.830400	0.794730	0.768630	
AZ006	A71	1.000000	0.886690	0.830720	0.798710	0.777760	
AZ006	A81	1.000000	0.888130	0.834880	0.798510	0.774810	

A11 TIME= 5.000



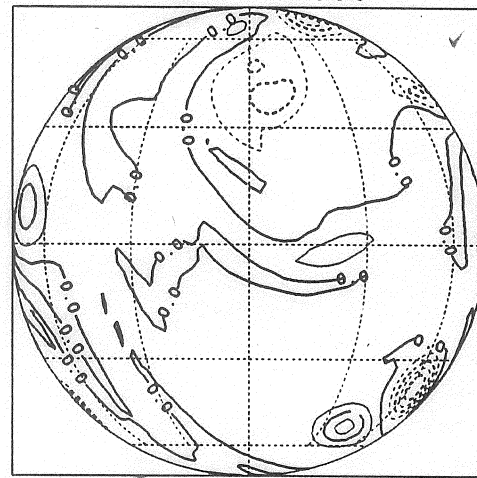
LON= 0

A21 TIME= 5.000



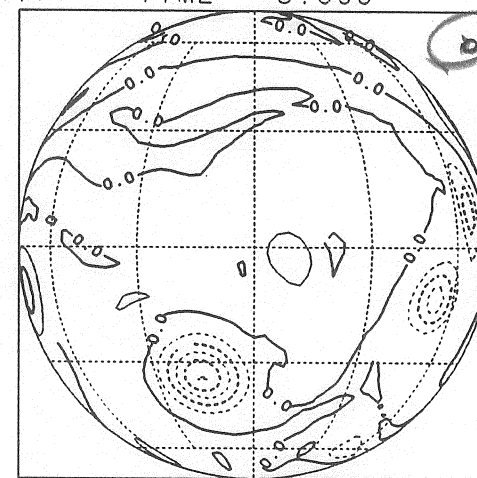
LON= 0

A31 TIME= 5.000



LON= 0

A41 TIME= 5.000



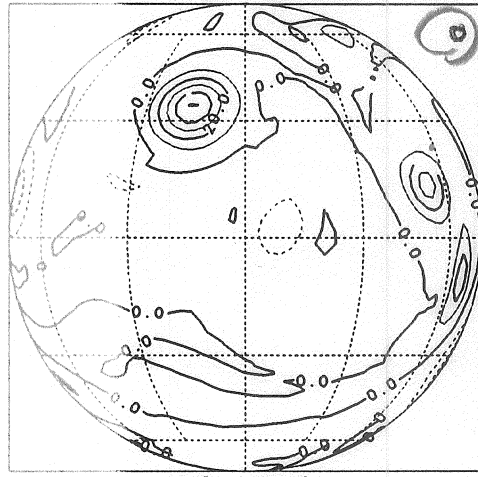
LON= 0

A51 TIME= 5.000



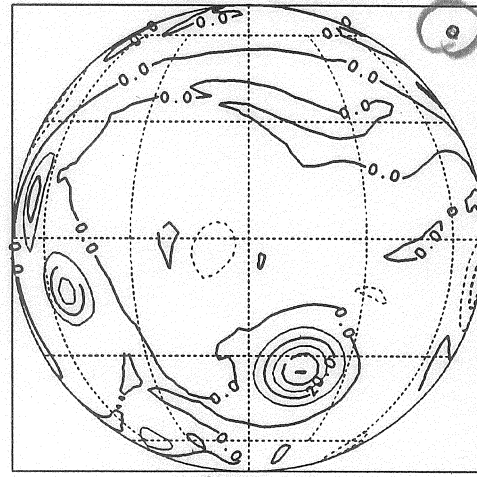
LON= 0

A61 TIME= 5.000



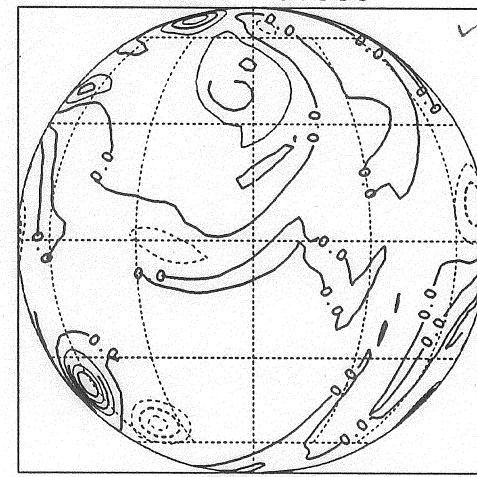
LON= 0

A71 TIME= 5.000



LON= 0

A81 TIME= 5.000



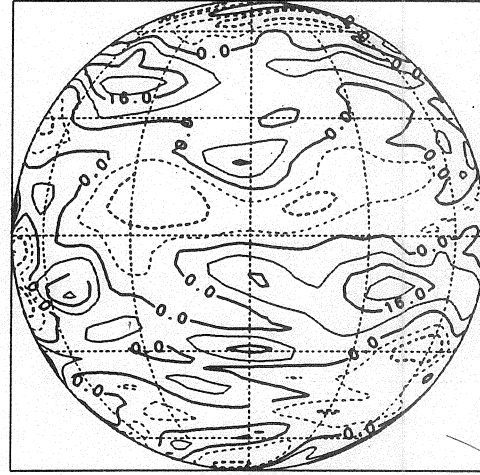
LON= 0

A11 TIME= 3.000



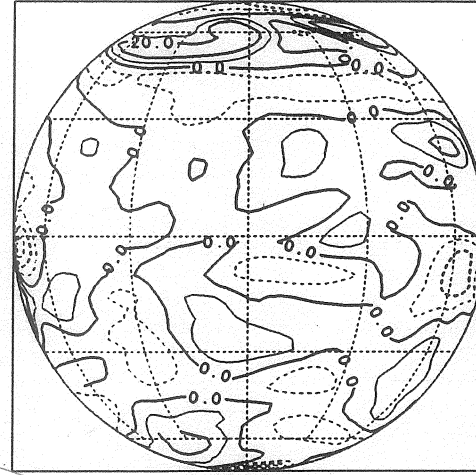
LON= 0

A21 TIME= 3.000



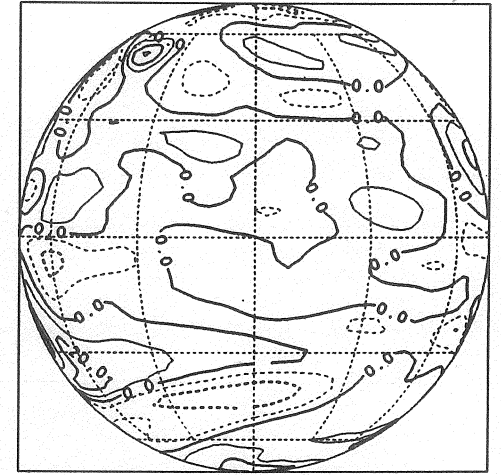
LON= 0

A31 TIME= 3.000



LON= 0

A41 TIME= 3.000



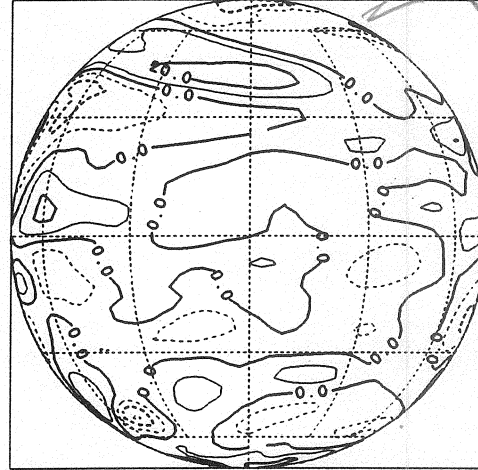
LON= 0

A51 TIME= 3.000



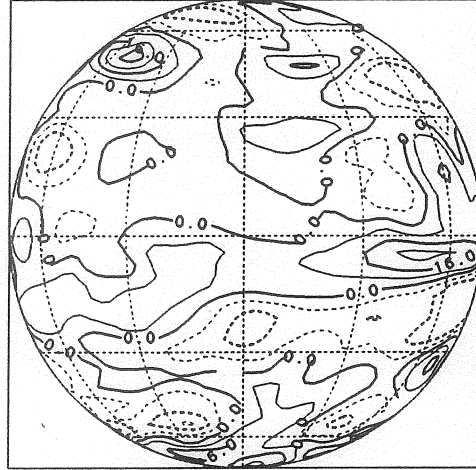
LON= 0

A61 TIME= 3.000



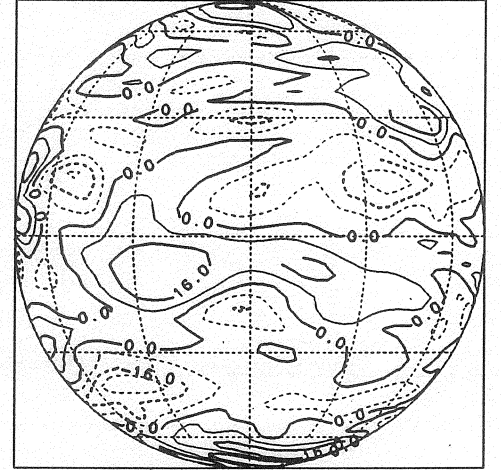
LON= 0

A71 TIME= 3.000



LON= 0

A81 TIME= 3.000



LON= 0

無次元化尺度の方
(結果は地球の半径程度の長さの尺度)

(仮定)

i) $\nu = 1$; $L = a^* = 6.37 \times 10^6 \text{ m}$

ii) $\Sigma^*(r_0) = (10 \text{ m/s})^2$

$$U^2 = \frac{1}{\nu^2} \frac{\Sigma^*(r_0)}{\Sigma(r_0)} = (10 \text{ m/s})^2$$

→ 1.0 である。

$\therefore U = 10 \text{ m/s}$

$$T = \frac{L}{U} = \frac{6.37 \times 10^6 \text{ m}}{10 \text{ m/s}} = 6.37 \times 10^5 \text{ s} \doteq 196.9 \text{ hrs}$$

$\doteq 7.37 \text{ days}$

実験 1.0 \times 7: Ω

$$\Omega \text{ (地球)} = T \Omega_e^* = 6.37 \times 10^5 \times 7.292 \times 10^{-5} \text{ s}^{-1} = 46.4$$

$R_{0e} \doteq 0.0108$

$\Omega = 0, 25, 50, 100, 200, 400$

$R_{rotation} = \frac{\Omega}{2\pi} = 0, 3.98, 7.96, 15.9, 31.8, 63.7$

$(R_0) = \omega, 0.02, 0.01, 0.005,$

四 初期值の特徵的大致.

初期値 \rightarrow

$$E(10) = 1.0$$

$$Q(10) = 180.0$$

無次元:

$$U_0 = \sqrt{E(10)} = 1.0$$

$$L_0 = \sqrt{E(10)/Q(10)} = 0.0745$$

$$T_0 = L_0/U_0 = 0.0745$$

次元:

$$U_0^* = U_0 U = 10 \text{ m/s}$$

$$L_0^* = L_0 L = 0.0745 \times 6.37 \times 10^6 \text{ m}$$

$$\approx 475 \text{ km}$$

$$T_0^* = T_0 T = 0.0745 \times 7.37 \text{ days}$$

$$\approx 0.549 \text{ days}$$

粘性係数

- ① hyper viscosity U_4 $T=4$: $U_2 = 0$
 (粘性の影響を24の部分に与える)

② 値の決め方

$$\frac{\partial U^*}{\partial t^*} \sim U_4^* \Delta^{*2} \rho^*$$

$$\frac{1}{M} \frac{\partial}{\partial t} \sim \frac{\rho^{*4}}{\rho^{*4}} U_4 \frac{1}{\rho^{*4}} (\Delta^2)_{max}$$

$$U_4 \sim \frac{1}{M^2 (M+1)^2} \Delta T$$

M : truncation
and wave number

$$\sim \frac{1}{85^2 \cdot 88^2} \cdot 0.0945$$

$$= 2.5 \times 10^{-7}$$

$$U_4 = 1 \times 10^{-6}$$

時間増分 Δt

○ 格子点法の CFL 条件:

$$|c| \frac{\Delta t^*}{\Delta x^*} \leq 1$$

$$|c| \sim U_0^* = U \quad \Delta x^* \sim \frac{2\pi a^*}{N \Delta \omega} \quad t_{\text{max}} \sim 2365$$

↑ transform parameter

$$\Delta t^* \leq \frac{2\pi a^*}{U_0^* N \Delta \omega}$$

$$\Delta t \leq \frac{2\pi a^*}{U N \Delta \omega} \cdot \frac{1}{T} = \frac{2\pi}{N \Delta \omega}$$

$$\begin{aligned} & \frac{1}{T} = \frac{U}{2a^*} \\ & = \frac{2\pi}{258} \sim 117.85 \\ & = 0.0245 \end{aligned}$$

○ 振動型常微分方程式

$$U = i \omega^* U$$

matrix, leapfrog stable for $\omega \Delta t \leq 1$

$$\Delta t \leq \frac{1}{\omega}$$

$$\Delta t = \boxed{5 \times 10^{-3}}$$

$$\Delta t^* \sim 535$$

$$I_{\text{MAX}} = 1000$$

$$t_{\text{max}} = \Delta t^* I_{\text{MAX}} = 5$$

$$t_{\text{max}}^* = 5 \times 7.37 \text{ days} = 36.85 \text{ days}$$

干端实验 20 对比.

parameters

$$a = 1$$

$$\Omega = 0, \quad 1 \sim 9 \quad \rightarrow \text{Re}$$

$$V_2 = 3 \times 10^{-8}$$

initial conditions

$$z(0) = 10^{-3}$$

$$j = 1, 5, \quad \beta = 0.5$$

Integration

$$\Delta t = 0.2$$

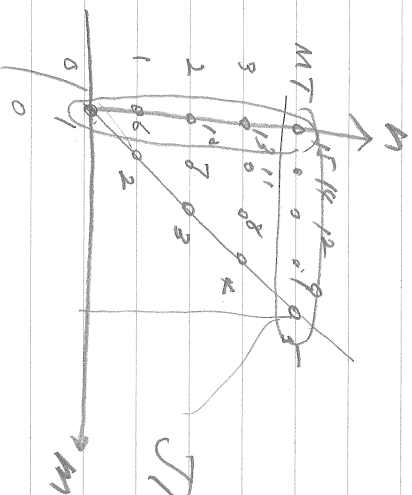
$$0 \leq t \leq 200$$

$$12,000$$

IMAXP = 10
IMAXE = 100
ISTPE = 10
ISDEL = 10

$$z(t) = \frac{1}{2} \sum_n \sum_m n(n+1) (4^n)^m (t) / 2$$

三角切斷の4点配列の1次元化



MT = 4 の場合

JMIN

JMIN(0:MT)
JMAX(0:MT)

$$JMIN(0) = 1$$

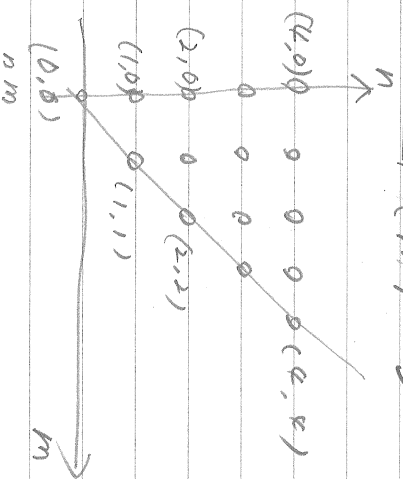
$$JMAX(0) = MT + 1$$

$$J = 1 \sim MT$$

$$JMIN(J) = JMAX(J-1) + 1$$

$$JMAX(J) = JMIN(J) + MT - J$$

ZPRN(M)



DO L = 0, MT

M = -1

DO J = JMIN(L), JMAX(L)

M = M + 1

N = M + L

ZDUT(J) = ZP(N, M)

CONT

① 無次元化速度

$$\begin{aligned} u^* &= -\frac{\sqrt{1-\mu^2}}{a^*} \frac{\partial \psi^*}{\partial \mu} \\ &= -\frac{1}{a^*} \frac{L^2}{r} \sqrt{1-\mu^2} \frac{\partial \psi}{\partial \mu} \\ &= -r \sqrt{1-\mu^2} \frac{\partial \psi}{\partial \mu} \end{aligned}$$

$$\begin{aligned} v^* &= \frac{1}{a^* \sqrt{1-\mu^2}} \frac{\partial \psi^*}{\partial \lambda} \\ &= r \sqrt{1-\mu^2} \frac{\partial \psi}{\partial \lambda} \end{aligned}$$

$$\therefore (u^*, v^*) = r \sqrt{1-\mu^2} (u, v)$$

$$u = -\sqrt{1-\mu^2} \frac{\partial \psi}{\partial \mu}$$

$$v = \frac{1}{\sqrt{1-\mu^2}} \frac{\partial \psi}{\partial \lambda}$$

2. 角運動量:

$$\begin{aligned} a^* \cos \delta \psi^* &= a^* \sqrt{1-\mu^2} \times (-r \sqrt{1-\mu^2}) \frac{\partial \psi}{\partial \mu} \\ &= -r a^* \sqrt{1-\mu^2} \frac{\partial \psi}{\partial \mu} \end{aligned}$$

① 潤度

$$\omega^* = \Delta^* \varphi^* = \frac{1}{a^{*2}} \frac{L^2}{r} \Delta \varphi = r^{*2} \frac{1}{r} \Delta \varphi$$

$$\omega = \Delta \varphi$$

・ 絶対潤度

$$\omega + 2Q\mu$$

② 運動エネルギーⁿ

$$\frac{1}{2} \omega^{*2} / r^2 = \frac{1}{2} (\omega^{*2} + v^{*2})$$

$$E(k, \mu, t) = \frac{1}{2} (\omega^2 + v^2)$$

③ インターフェイス

$$\omega^{*2} = r^{*4} \frac{1}{r^2} (\Delta \varphi)^2$$

$$\omega^2 = (\Delta \varphi)^2$$

記号:

zonal mean: $\bar{a} = \frac{1}{2\pi} \int_0^{2\pi} a \, d\lambda$

deviation from zonal mean: $a' = a - \bar{a}$

ensemble (time) mean: $\langle a \rangle = \frac{1}{N} \sum_{n=1}^N a_n$

deviation from ensemble mean: $a^* = a - \langle a \rangle$

④ momentum (\leftarrow grad ψ)

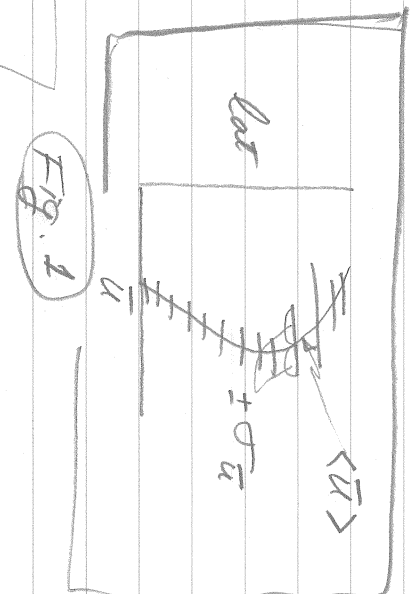
① zonal mean

CMU

1-1 $\bar{u}(\phi, t)$

$\langle \bar{u} \rangle = 0$

$\langle \bar{u} \rangle(\phi)$



$\bar{u}^*(\phi, t) \rightarrow \sigma_{\bar{u}}(\phi) = \sqrt{\langle \bar{u}^{*2} \rangle}$

② deviation from z.m.

2-1 $u'(\lambda, \phi, t)$

r.m.s $u' \rightarrow \delta u(\phi, t) \equiv \sqrt{\overline{u'^2}}$

$\langle \delta u \rangle(\phi)$, $\sigma_{\delta u}(\phi) = \sqrt{\langle \delta u^{*2} \rangle}$

Fig. 2

$$\boxed{2-2} \quad \psi'(x, \phi, t)$$

$$\langle \delta v \rangle(\phi), \quad \sigma_{\delta v}(\phi)$$

Fig. 3

$$\boxed{2-3}$$

$$\text{ratio } \langle \delta v \rangle / \langle \delta u \rangle$$

"弱" 相关性

$$r(\phi) = \frac{\langle \delta v \rangle(\phi)}{\langle \delta u \rangle(\phi)}$$

Fig. 4

① Energy

(\leftarrow / grad ϕ / 2)

$$E(x, \phi, t) = \frac{1}{2} (v^2 + w^2)$$

① small mean

$$\boxed{3-1} \quad \bar{E}(x, t)$$

$$\langle \bar{E} \rangle(\phi), \quad \sigma_{\bar{E}}(\phi)$$

Fig. 5

② deviation from z.m.

$$\boxed{4-1} \quad E'(x, \phi, t)$$

$$\delta E(x, t) = \sqrt{\bar{E}'^2}$$

$$\langle \delta E \rangle(\phi), \quad \sigma_{\delta E}(\phi)$$

Fig. 6

NO.

27

2-4

< r.m.s. u / r.m.s. u >

$$\text{r.m.s. } u = \sqrt{u^2} = \delta u$$

$$\begin{aligned} \text{r.m.s. } u &= \sqrt{\overline{u^2}} = \sqrt{\overline{u^2} + \overline{u'^2}} \\ &= \sqrt{\overline{u^2} + (\delta u)^2} \end{aligned}$$

① vorticity ($\nabla \times \Delta \phi$)

$$\omega(x, y, z, t) = \Delta \phi$$

① zonal mean

$$\boxed{5-1} \quad \bar{\omega}(y, z, t)$$

$$\langle \bar{\omega} \rangle (y), \quad \sigma_{\bar{\omega}}(y)$$

Fig. 7

② deviation from z.m.

$$\boxed{6-1} \quad \omega'(x, y, z, t) \rightarrow \delta \omega(x, y, z, t) = \sqrt{\overline{\omega'^2}}$$

$$\langle \delta \omega \rangle (y), \quad \sigma_{\delta \omega}(y)$$

Fig. 8

③ anisotropy ($\nabla \times (\Delta \phi)^2$)

$$Q(x, y, z, t) = (\Delta \phi)^2$$

① zonal mean

$$\boxed{7-1} \quad \bar{Q}(y, z, t)$$

$$\langle \bar{Q} \rangle (y), \quad \sigma_{\bar{Q}}(y)$$

Fig. 9

② deviation from z.m.

$$\boxed{8-1} \quad Q'(x, y, z, t) \rightarrow \delta Q(x, y, z, t) = \sqrt{\overline{Q'^2}}$$

$$\langle \delta Q \rangle (y), \quad \sigma_{\delta Q}(y)$$

Fig. 10

角運動量:

$$M(\varphi, t) = a \cos \varphi \bar{u}(\varphi, t)$$

速度:

$$u = \theta r \cdot \text{rot } u$$

$$= \frac{1}{a \cos \varphi} \left\{ \frac{\partial u}{\partial t} - \frac{\partial}{\partial \varphi} (\cos \varphi u) \right\}$$

$$\bar{u} = \frac{-1}{a \cos \varphi} \frac{\partial}{\partial \varphi} (\cos \varphi \bar{u}) \quad \bar{u} = -\frac{\sqrt{1-\mu^2}}{a} \frac{d\bar{u}}{d\mu}$$

$$= -\frac{1}{a} \frac{d\bar{u}}{d\mu}$$

$$M = \text{const} \iff \bar{u} = 0$$

//

Rayleigh 条件

帶狀流が不安定になる必要條件:

$$T_1 - 1 < \mu < 1 \quad 2 \cdot d\bar{u}/d\mu + 2 \Omega a - \text{符号} \geq \rho \lambda \geq 3$$

$$\frac{d\bar{u}}{d\mu} = \frac{1}{\cos \varphi} \frac{d}{d\varphi} \left\{ \frac{-1}{a \cos \varphi} \frac{d}{d\varphi} \left(-\frac{\cos \varphi}{a} \frac{d\bar{u}}{d\varphi} \right) \right\}$$

$$\mu = \sin \varphi \quad = \frac{1}{\cos \varphi} \frac{d}{d\varphi} \left\{ \frac{1}{a^2 \cos \varphi} \frac{d}{d\varphi} (\cos \varphi \frac{d\bar{u}}{d\varphi}) \right\}$$

$$\begin{aligned} d\mu &= \cos \varphi d\varphi \\ &= \frac{1}{a^2 \cos \varphi} \frac{d}{d\varphi} \left\{ \frac{1}{\cos \varphi} \left(-\sin \varphi \frac{d\bar{u}}{d\varphi} + \cos \varphi \frac{d^2 \bar{u}}{d\varphi^2} \right) \right\} \\ &= \frac{1}{a^2 \cos \varphi} \frac{d}{d\varphi} \left(\frac{d^2 \bar{u}}{d\varphi^2} - \tan \varphi \frac{d\bar{u}}{d\varphi} \right) \end{aligned}$$

 $\langle \bar{u} + 2\Omega \mu \rangle \rightarrow$ 単増: stable

Rms

$$k_p = \sqrt{\beta/2U}$$

$$\beta = \frac{1}{a} \frac{df}{d\phi} = \frac{2R}{a} \cos\phi$$

U: r.m.s. particle speed

$$\cdot \frac{1}{2} U^2 = \varepsilon(10) = 1$$

$$U = \sqrt{2}$$

$$\cdot a = 1$$

$$k_p = \sqrt{2 \cos\phi / \sqrt{2}}$$

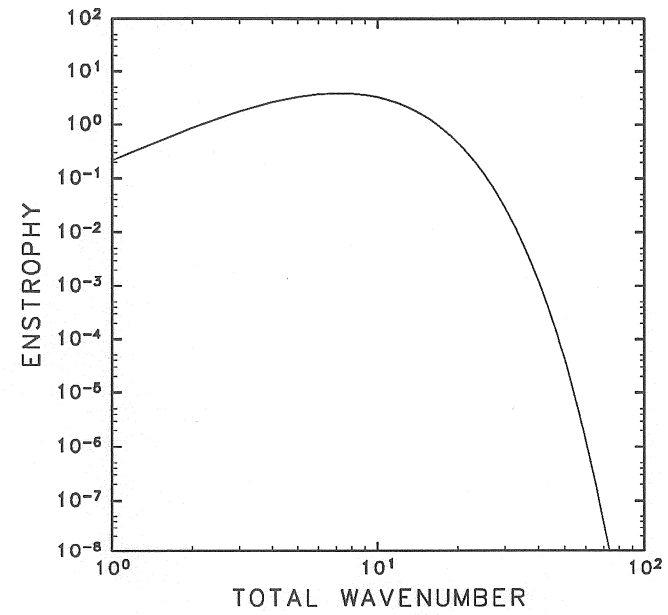
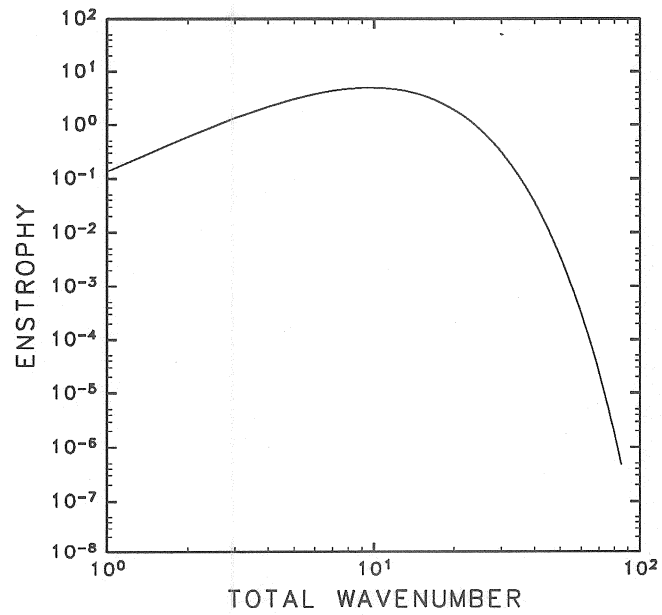
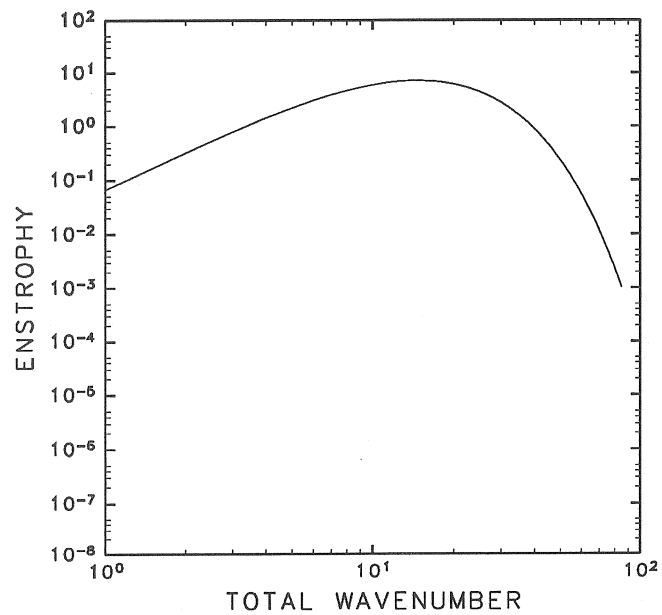
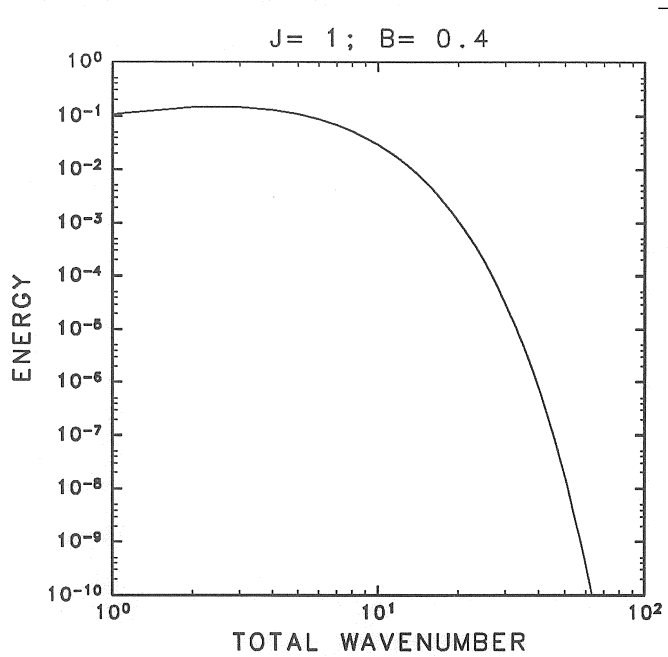
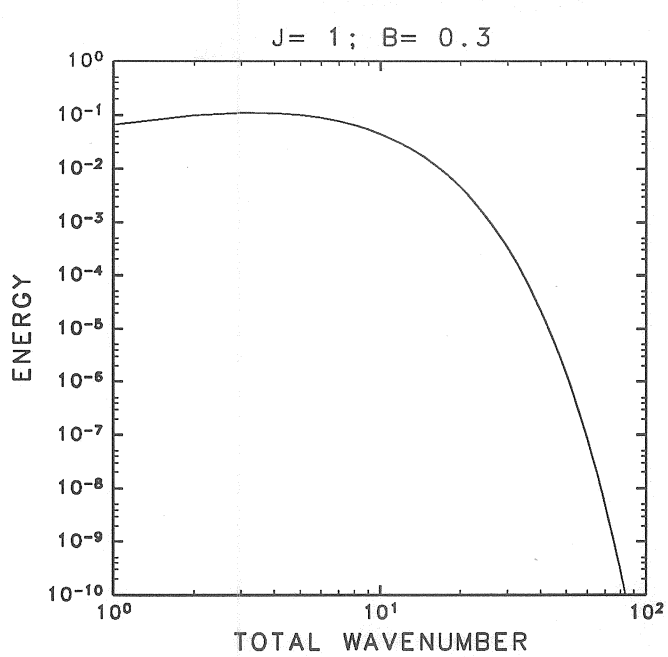
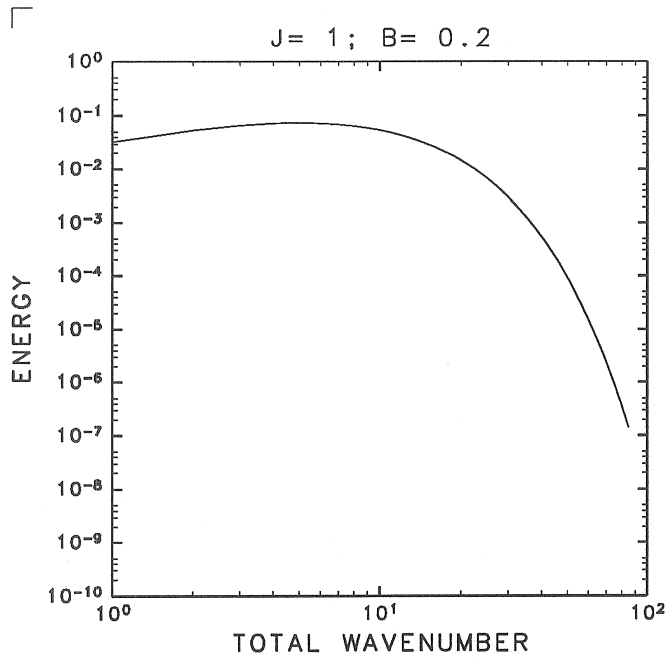
$$\# \text{ } \cos\phi = 1$$

$$k_p = \sqrt{2} / \sqrt{2}$$

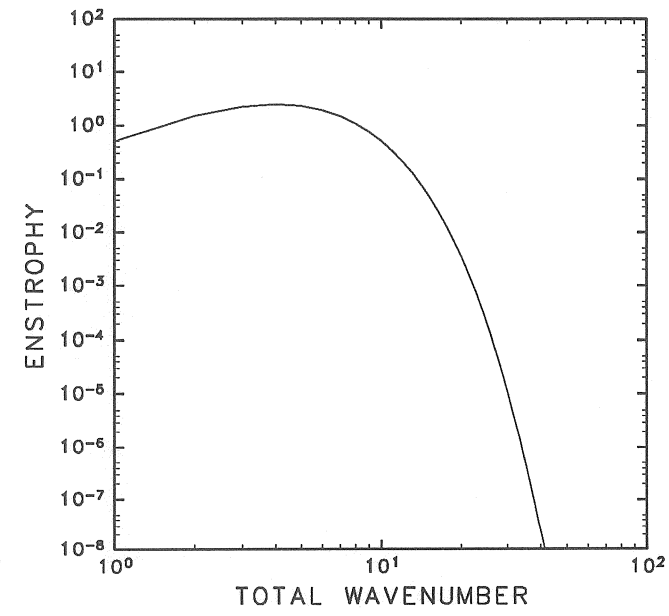
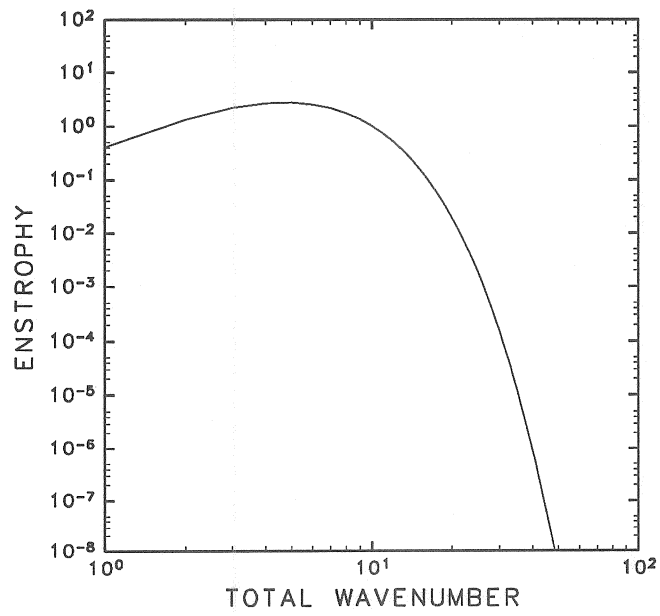
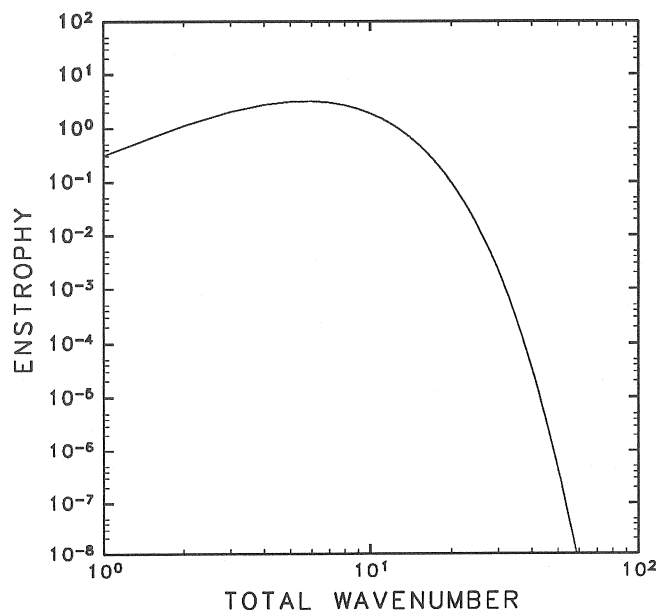
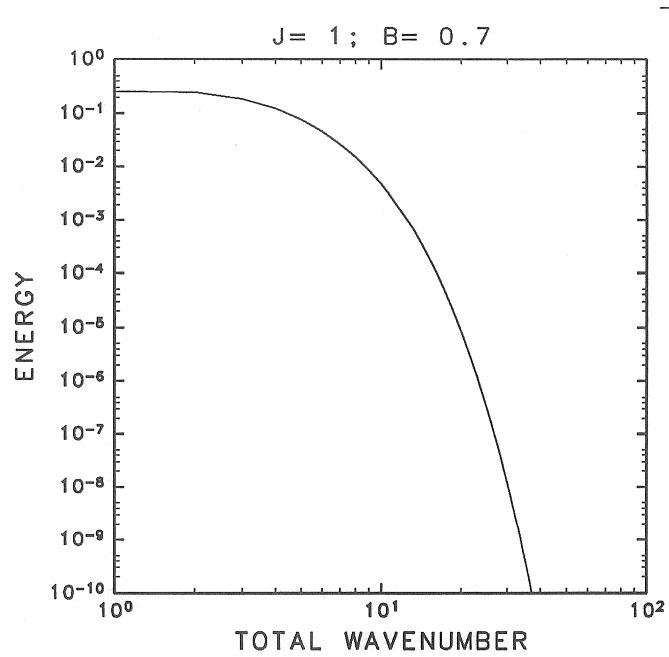
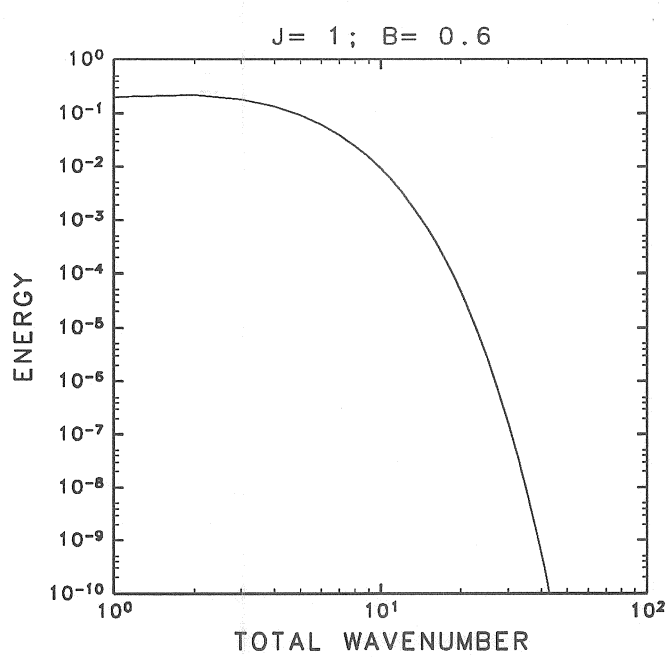
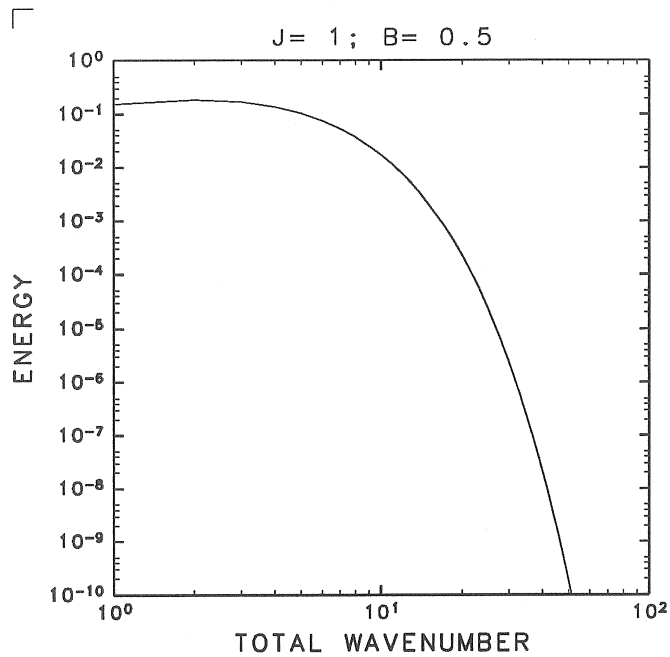
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k_p	0	4.2	5.9	8.4	11.8	16.8

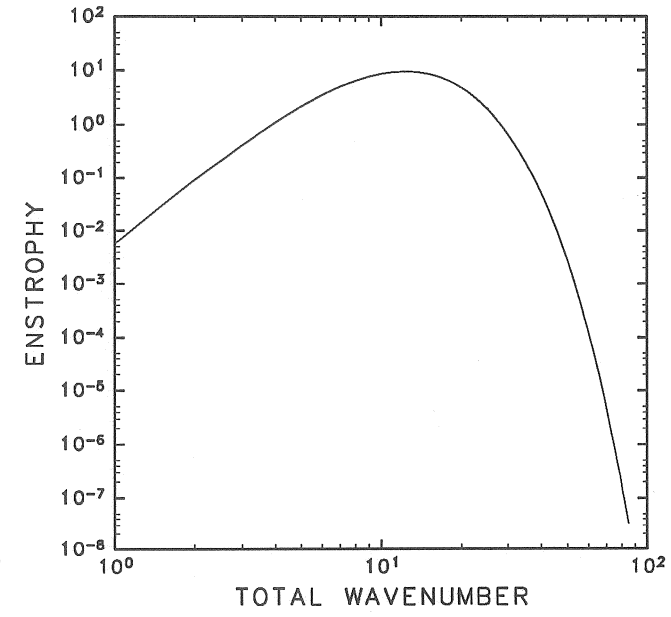
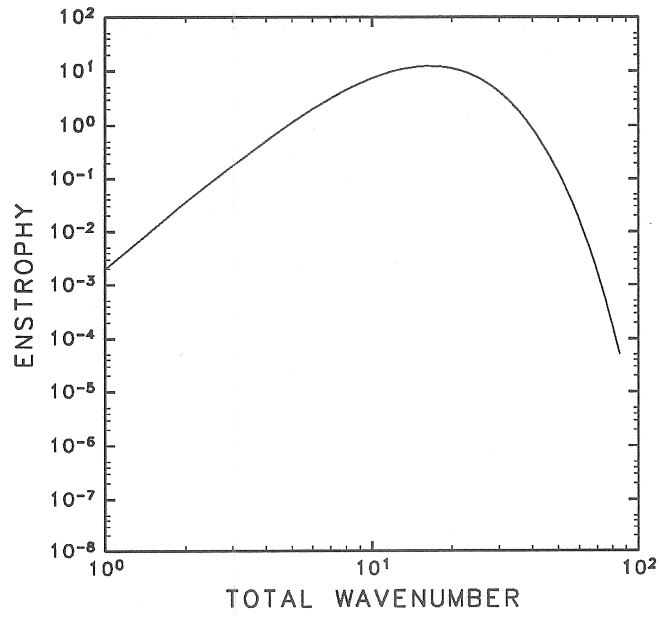
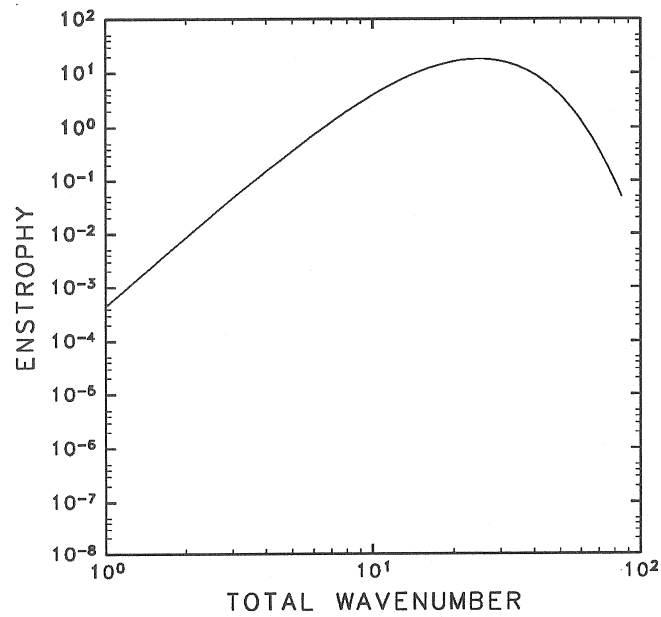
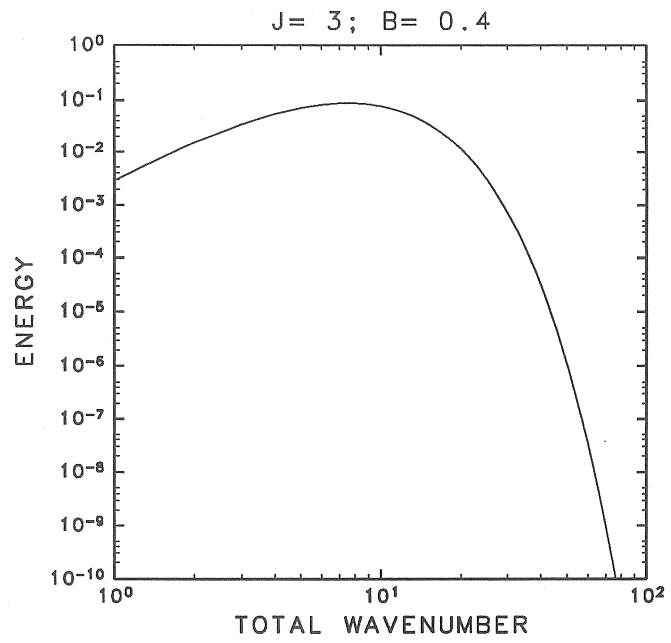
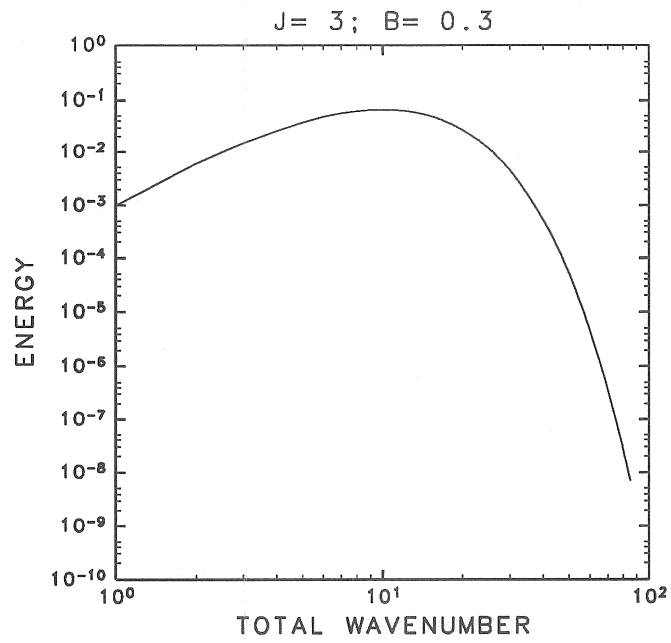
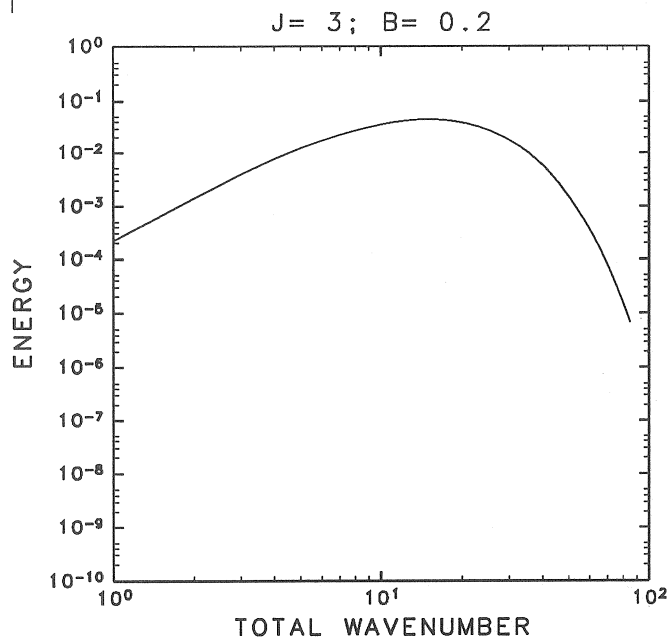
$$30^\circ \quad \cos\phi = 0.866$$

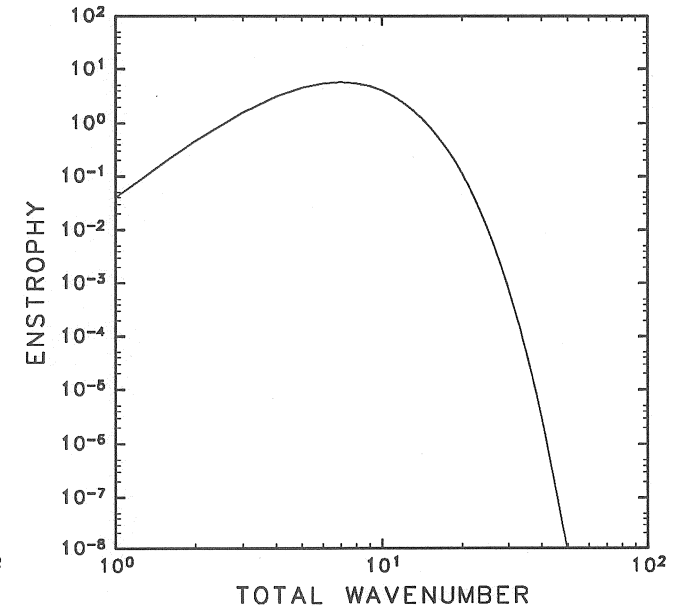
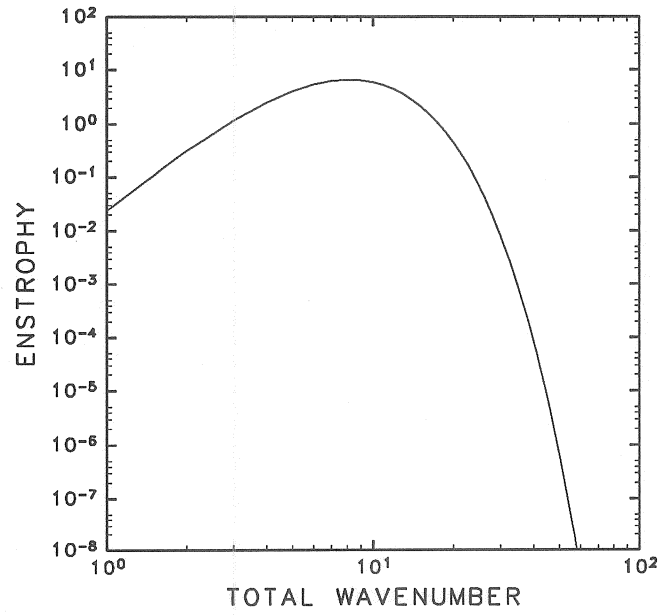
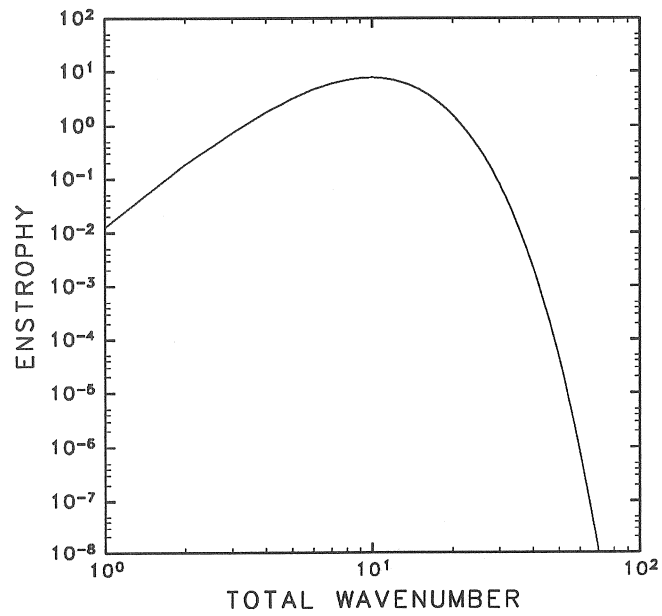
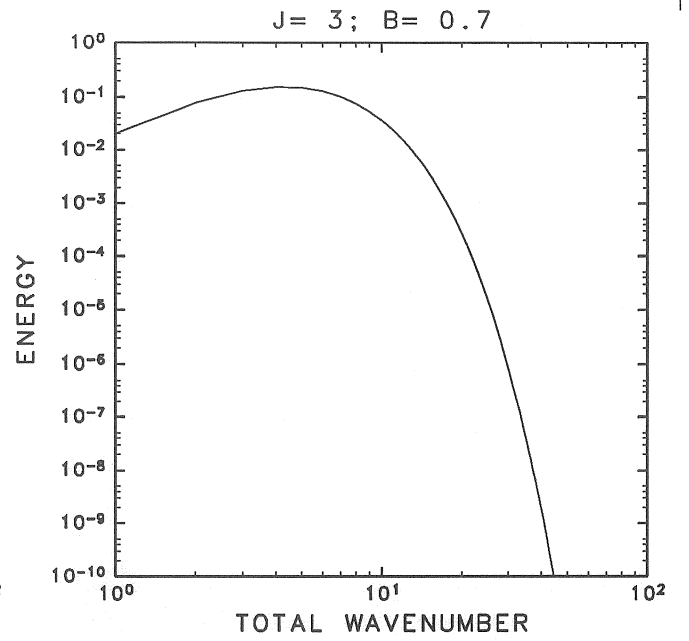
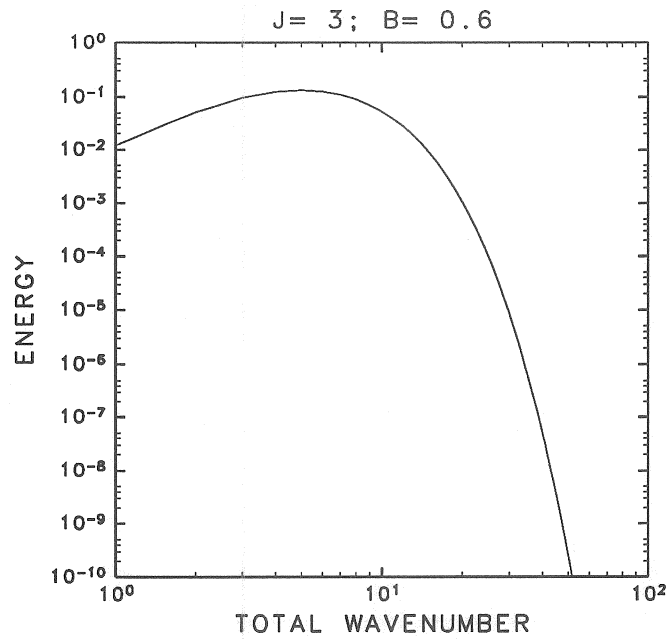
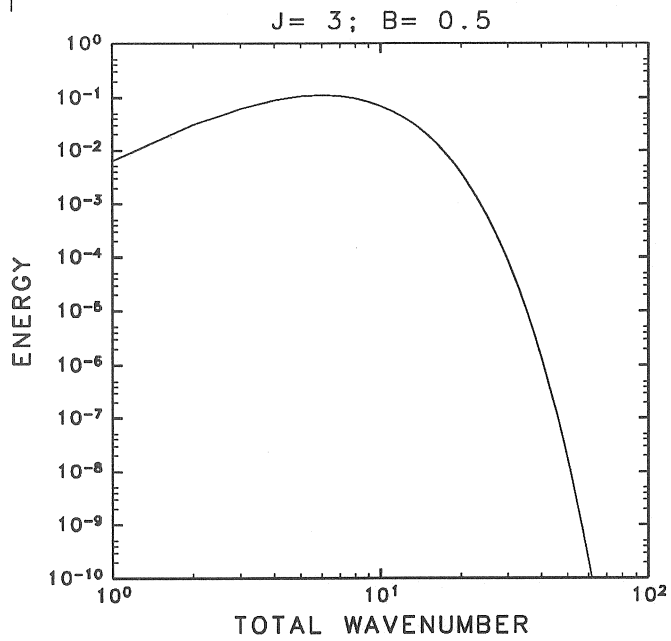
$$k_p \quad 0$$

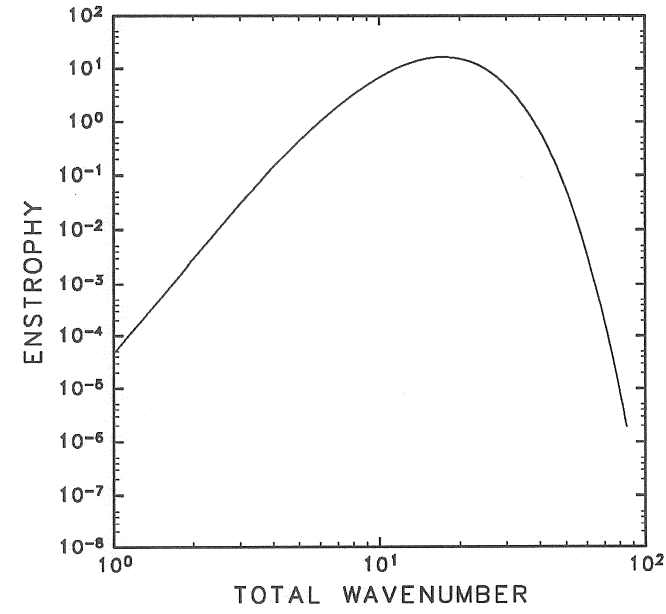
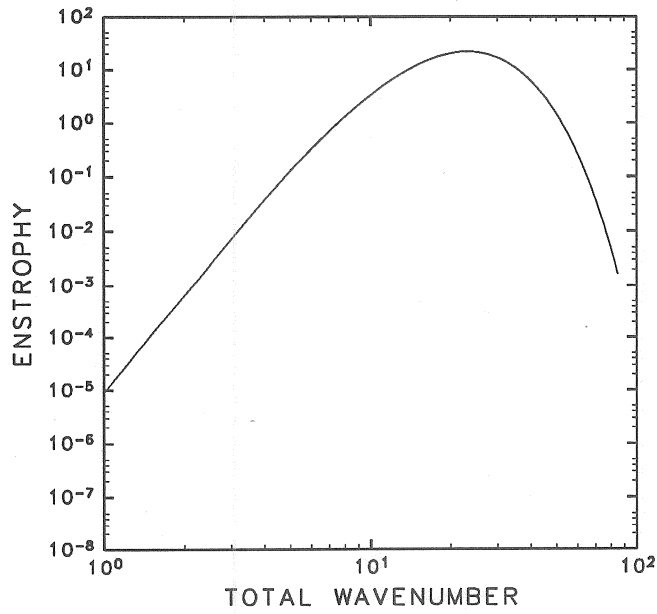
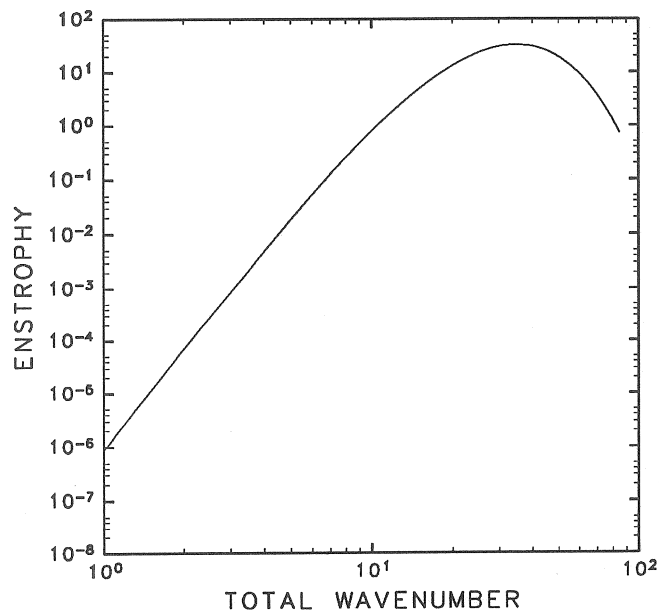
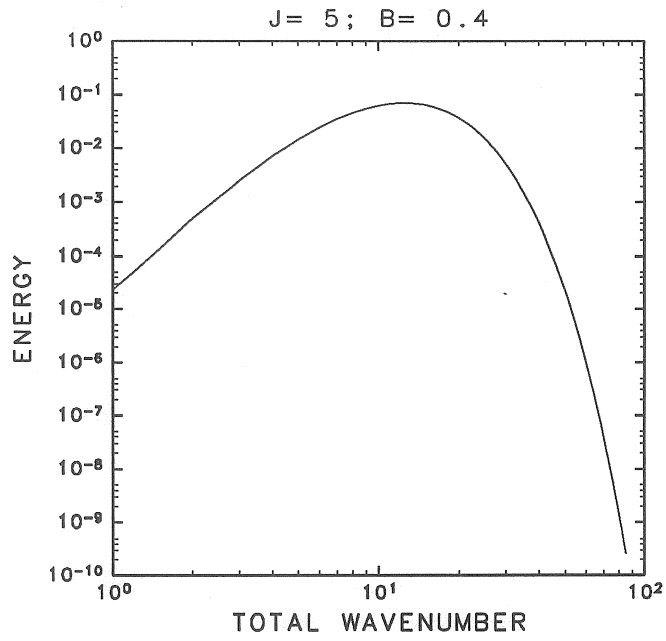
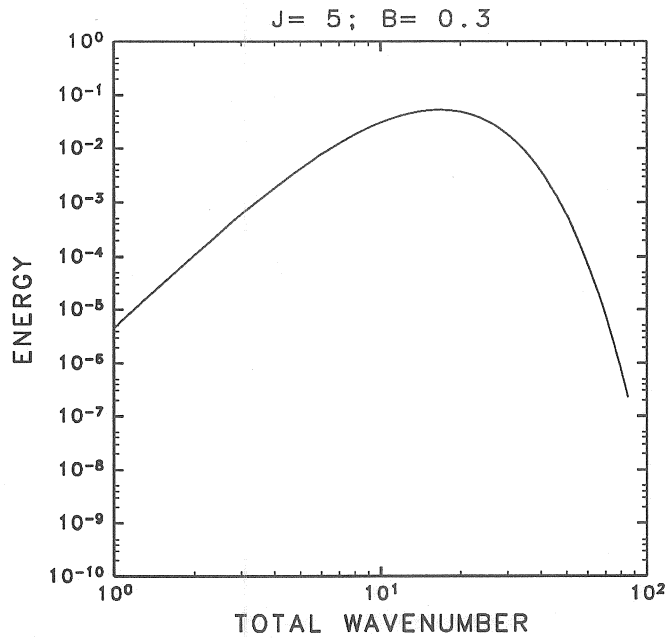
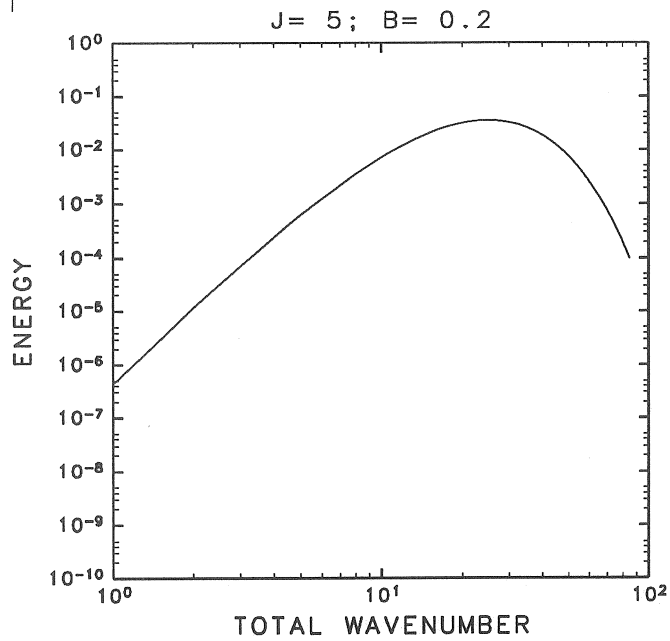


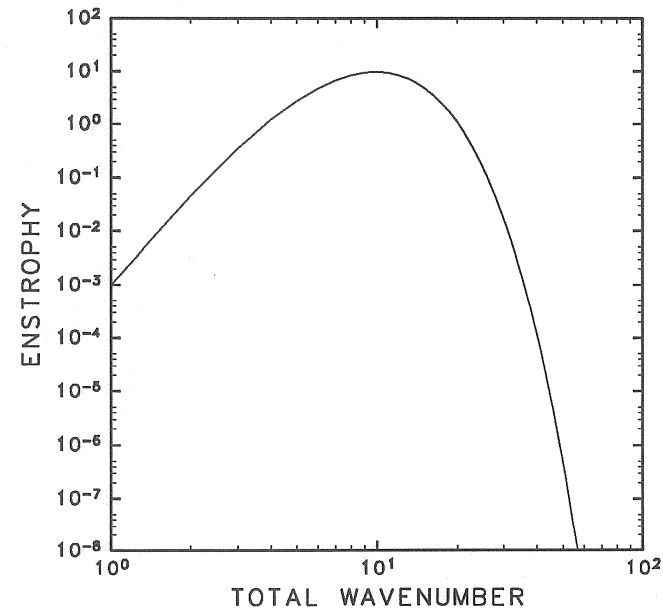
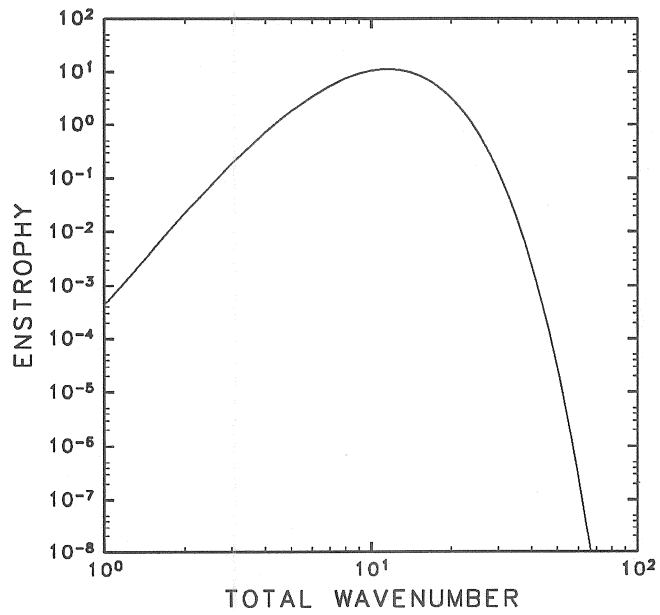
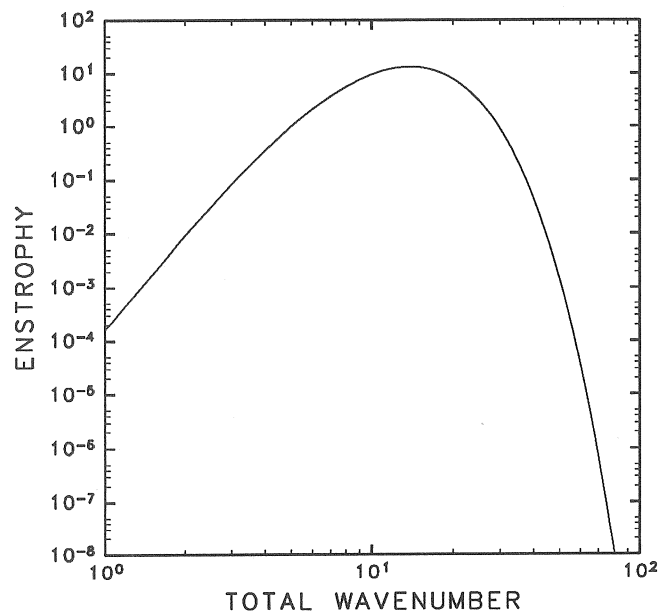
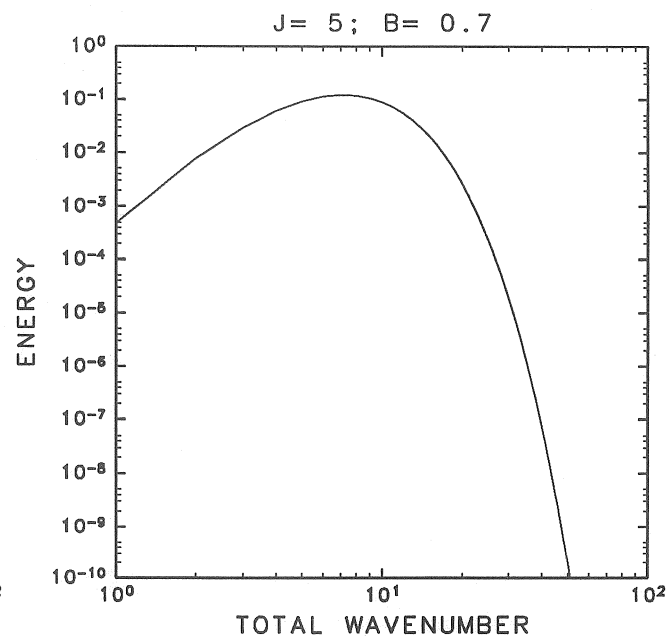
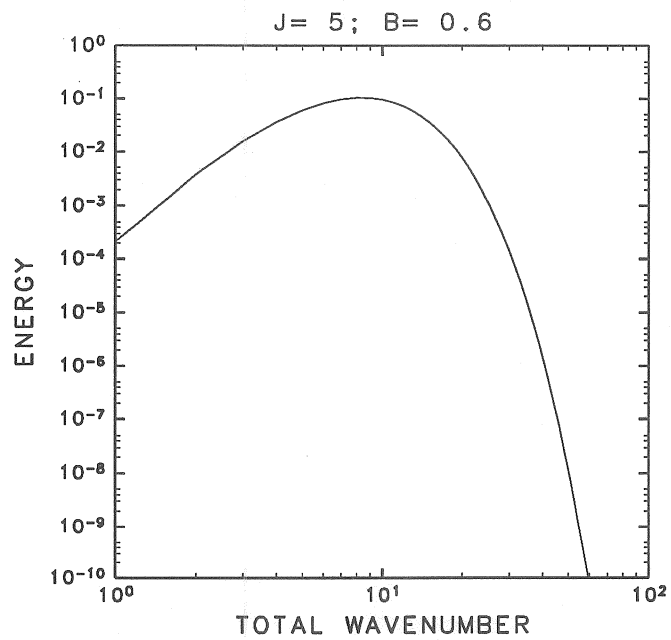
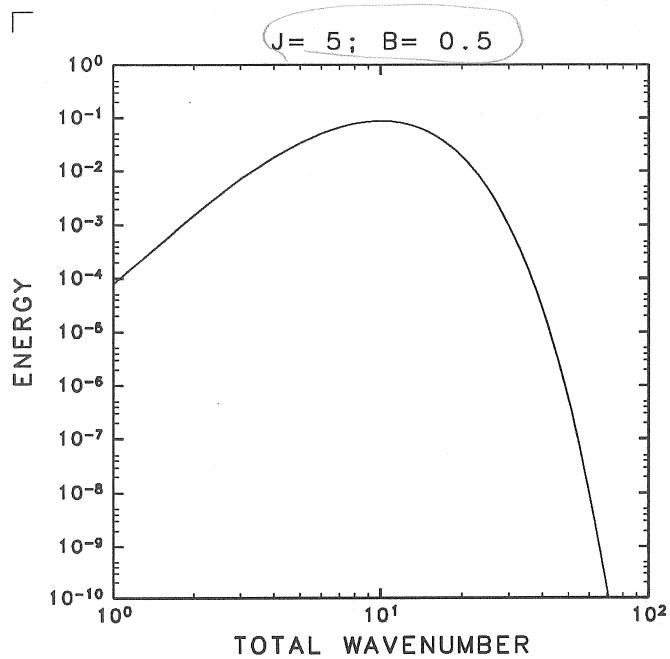
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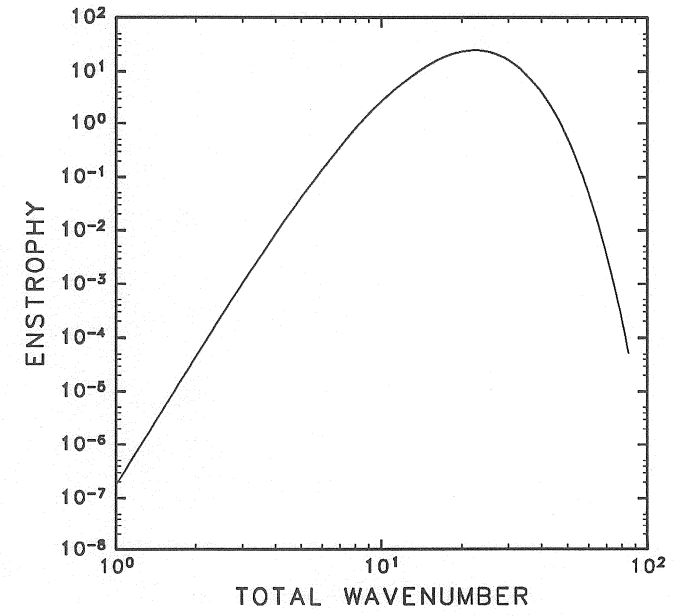
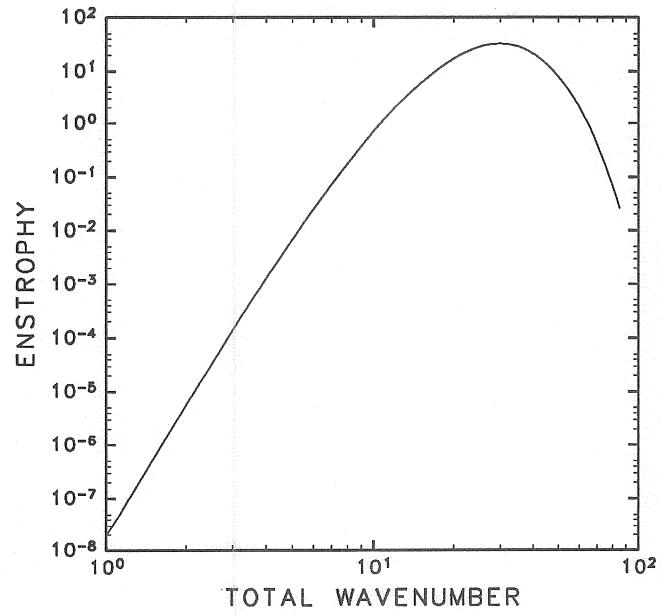
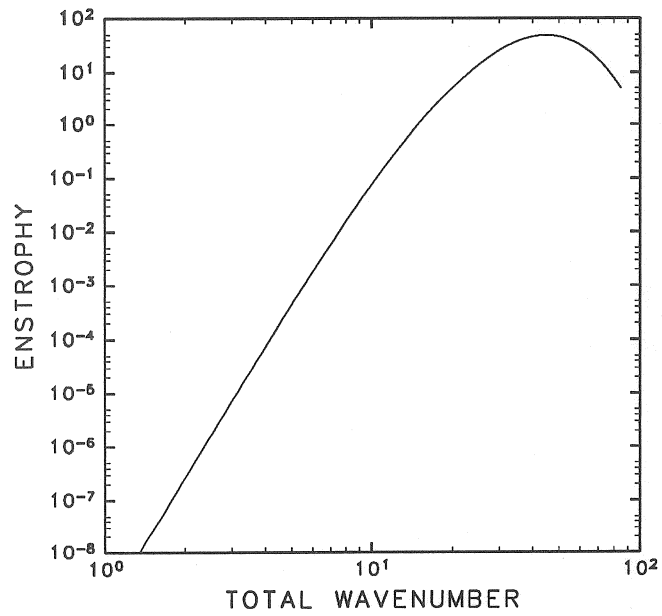
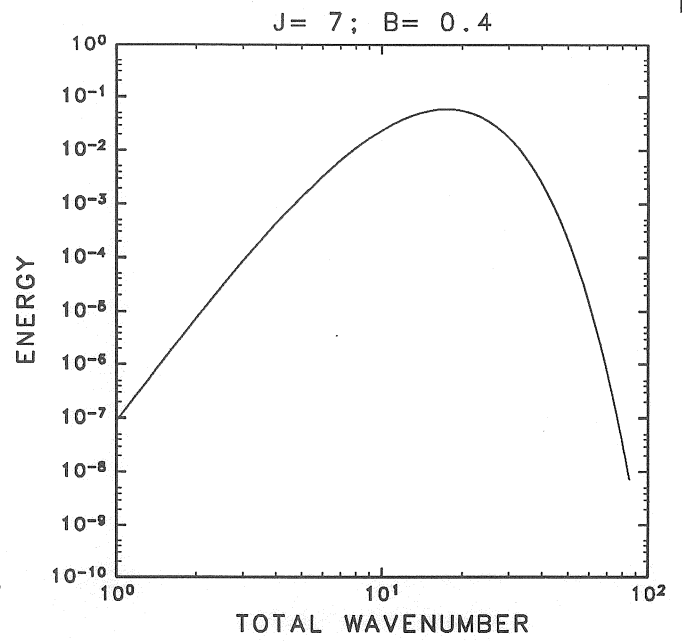
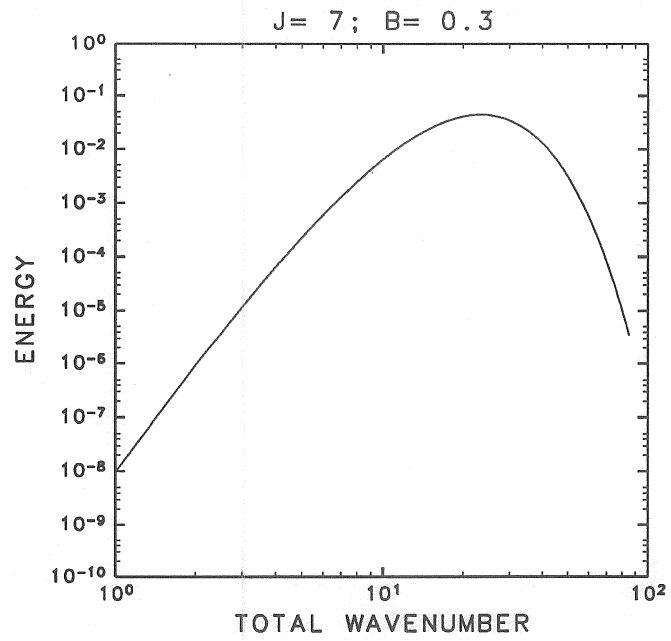
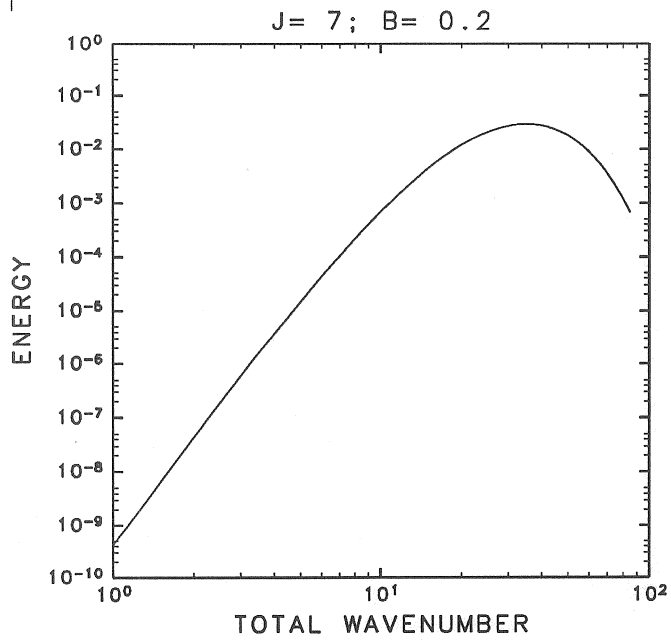


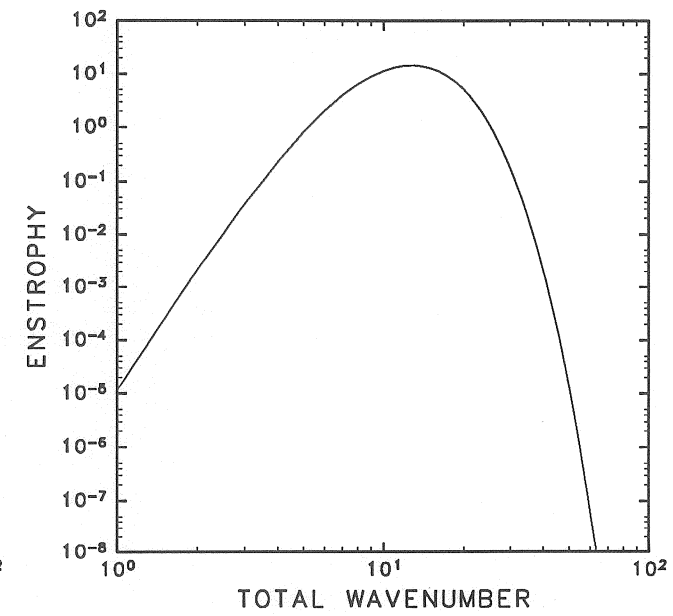
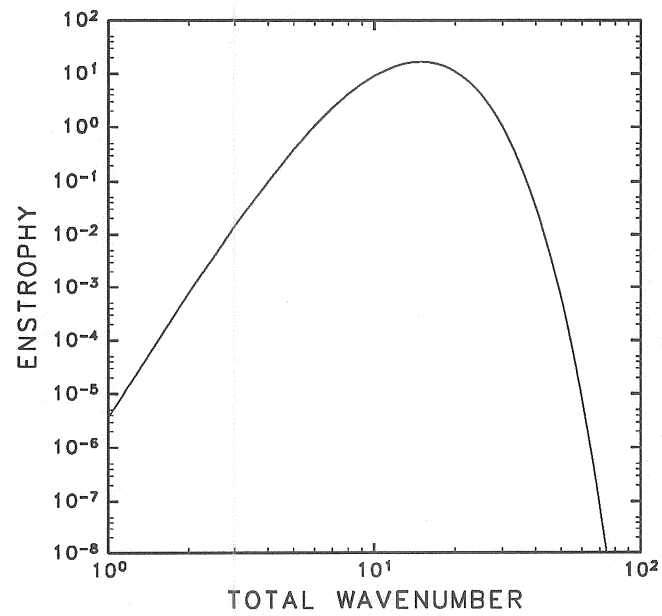
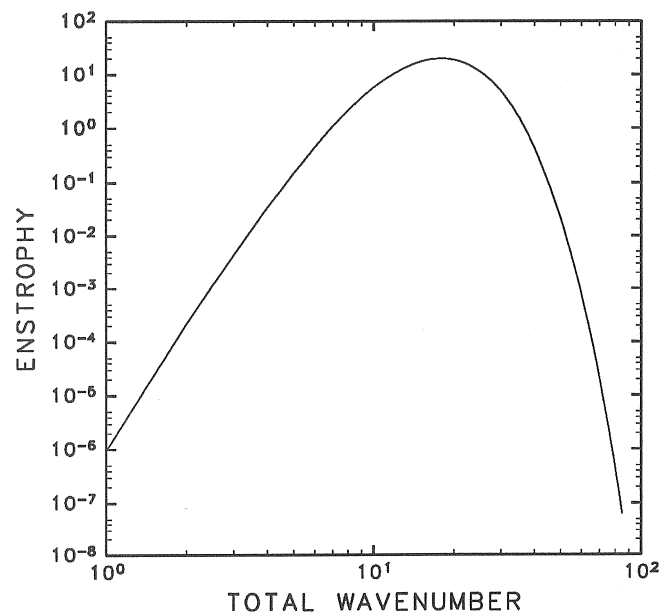
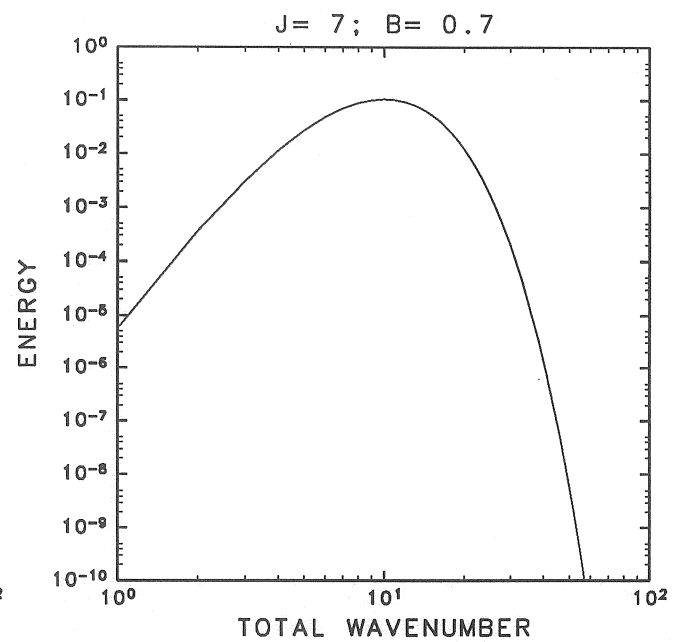
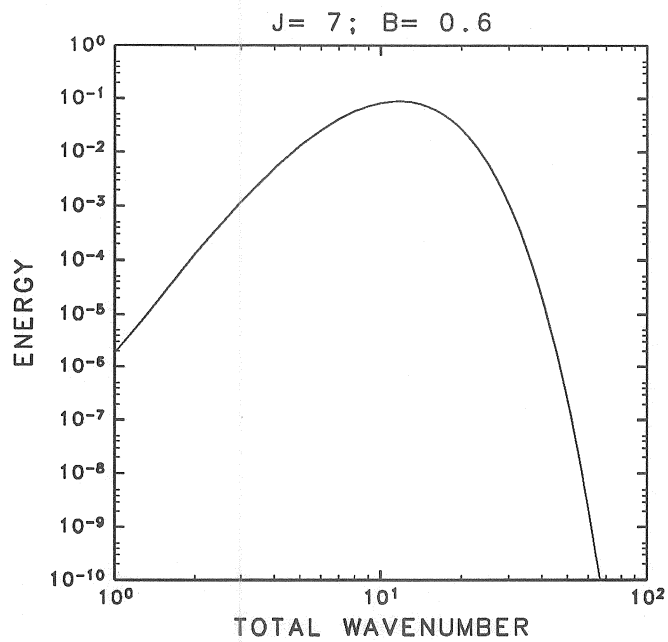
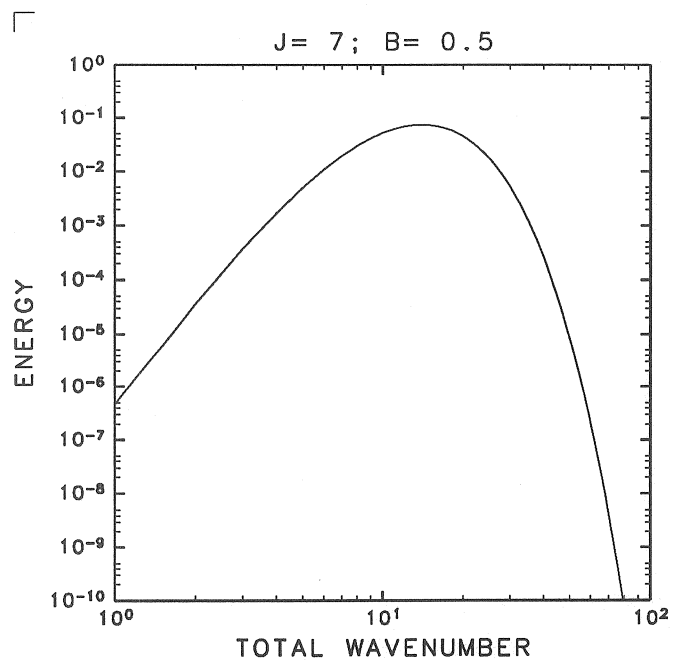












print-J

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.40134E-01 J = 1 B = 0.20
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.16053E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.78927E-01
TIME SCALE = 0.78927E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.90677E-01 J = 1 B = 0.30
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.73885E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.11634E+00
TIME SCALE = 0.11634E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.16214E+00 J = 1 B = 0.40
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.43070E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.15237E+00
TIME SCALE = 0.15237E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.25525E+00 J = 1 B = 0.50
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.28589E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.18702E+00
TIME SCALE = 0.18702E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.37093E+00 J = 1 B = 0.60
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.20608E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.22028E+00
TIME SCALE = 0.22028E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.51034E+00 J = 1 B = 0.70
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.15730E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.25214E+00
TIME SCALE = 0.25214E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.26668E-03 J = 3 B = 0.20
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.51970E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.43866E-01
TIME SCALE = 0.43866E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>
A = 0.13500E-02 J = 3 B = 0.30
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.23555E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.65156E-01
TIME SCALE = 0.65156E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.42665E-02 J = 3 B = 0.40
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.13500E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.86068E-01
TIME SCALE = 0.86068E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.10416E-01 J = 3 B = 0.50
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.87993E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.10660E+00
TIME SCALE = 0.10660E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.21596E-01 J = 3 B = 0.60
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.62212E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.12678E+00
TIME SCALE = 0.12678E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.40005E-01 J = 3 B = 0.70
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.46517E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.14662E+00
TIME SCALE = 0.14662E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.53367E-06 J = 5 B = 0.20
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.10753E+04
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.30496E-01
TIME SCALE = 0.30496E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.60750E-05 J = 5 B = 0.30
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.48666E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.45330E-01
TIME SCALE = 0.45330E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.34133E-04 J = 5 B = 0.40
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.27750E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.60030E-01
TIME SCALE = 0.60030E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.13021E-03 J = 5 B = 0.50
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.18000E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.74536E-01
TIME SCALE = 0.74536E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.38880E-03 J = 5 B = 0.60
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.12667E+03

VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.88852E-01
TIME SCALE = 0.88852E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.98041E-03 J = 5 B = 0.70
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.94286E+02
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.10299E+00
TIME SCALE = 0.10299E+00

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.51054E-09 J = 7 B = 0.20
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.18041E+04
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.23543E-01
TIME SCALE = 0.23543E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.13018E-07 J = 7 B = 0.30
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.82656E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.34783E-01
TIME SCALE = 0.34783E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.13003E-06 J = 7 B = 0.40
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.47000E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.46127E-01
TIME SCALE = 0.46127E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.77505E-06 J = 7 B = 0.50
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.30400E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.57354E-01
TIME SCALE = 0.57354E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.33326E-05 J = 7 B = 0.60
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.21333E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.68465E-01
TIME SCALE = 0.68465E-01

<<< DYNAMICAL CHARACTERISTICS OF INITIAL STATE >>>

A = 0.11438E-04 J = 7 B = 0.70
TOTAL ENERGY = 0.10000E+01 TOTAL ENSTROPHY = 0.15837E+03
VELOCITY SCALE = 0.10000E+01
LENGTH SCALE = 0.79463E-01
TIME SCALE = 0.79463E-01

```

1 PROGRAM/INIT
2 *****
3 *
4 * SET GAUSSIAN LATITUDES AND LEGENDRE FUNCTIONS
5 *
6 * This program computes Gaussian latitudes and Legendre functions
7 * at the latitudes.
8 *
9 * coded by S. Yoden(Kyoto Univ.)
10 * May, 1990
11 * *****
12 IMPLICIT REAL* 8(A-H,O-Z)
13
14 * transform resolution parameters
15 * grid resolution
16 * PARAMETER ( NION= 128, NIAT= 64, NIOH=NION/2, NIAH=(NIAT+1)/2 )
17 * spectral resolution
18 * PARAMETER ( MT= 42 )
19 * parameters
20 * NION = number of longitudes
21 * NIAT = number of latitudes
22 * NIAH = number of latitudes between pole and equator
23 * MT = maximum zonal wavenumber for triangle truncation
24
25 * DIMENSION COLAT(NIAT), GW(NIAT)
26 * DIMENSION DCCLT(NIAT)
27 * DIMENSION PMN(NIAT,0:MT,0:MT), DPMN(NIAT,0:MT,0:MT)
28
29 * COLAT : colatitude(deg) of the Gaussian grids
30 * GW : Gaussian weight
31 * DCCLT : double precision of cos(COLAT)
32 * PMN : normalized Legendre functions
33 * DPMN : d(PMN)/d(DCCLT)
34
35 CHARACTER WDATA*50
36 DATA WDATA/'xxxx'/'
37
38 * computation of Gaussian latitudes
39 CALL GAUSS( COLAT, GW, DCCLT )
40
41 * computation of Legendre functions
42 CALL LGNDR( DCCLT, GW, PMN, DPMN )
43
44 * storage of Gaussian weights and Legendre functions
45 C OPEN (1, FILE=WDATA, FORM='UNFORMATTED')
46 C WRITE(1) MT, NIAT, COLAT, GW, PMN, DPMN
47 C CLOSE(1)
48
49 STOP
50 END
51 *****
52 SUBROUTINE GAUSS( DCOLAT, DGW, DCCLT )
53 *
54 * GAUSS gives the Gaussian latitudes by finding the roots
55 * of the ordinary Legendre polynomial of degree NIAT
56 * using Newton's iteration method.
57 * It also computes the associated Gaussian weights.
58 * The solutions are symmetric with respect to the equator
59 * so that only half of the whole domain is computed.
60 *
61 * On exit: for each Gaussian latitude
62 * DCOLAT - the colatitudes in radians
63 * DGW - the Gaussian weights
64 * DCCLT - quadruple precision of cos(colatitude)
65 * *****
66

```

```

67      IMPLICIT REAL* 8(A-H,O-Z)
68
69      * transform resolution parameters
70      * grid resolution
71      PARAMETER ( NION= 128, NLAT= 64, NLOH=NION/2, NLAH=(NLAT+1)/2 )
72      * spectral resolution
73      PARAMETER ( MT= 42 )
74
75      DIMENSION DCOLAT(NLAT), DGW(NLAT)
76      DIMENSION DCCLT (NLAT)
77      *-----
78      PI      = 4.D0*ATAN(1.D0)
79      RADINV  = 180.D0/PI
80
81      * convergence criterion for iteration
82      EPS    = 1.D-15
83      XPREV  = 1.D10
84
85      * loop over latitudes, from pole to equator -----
86      DO 10 L=1,NLAH
87
88      * set first guess
89      X = SIN( PI * (NLAT+1.D0-2.D0*L) / (2.D0*NLAT+1.D0) )
90
91      * Newton method
92      ITRMAX = 500
93      DO 20 ITR=1,ITRMAX
94      PJ0 = 1.D0
95      PJ1 = X
96
97      DO 30 J=1,NLAT-1
98      PJ2 = ( (2.D0*J+1.D0)*X*PJ1 - J*PJ0 ) / (J+1.D0)
99      PJ0 = PJ1
100     PJ1 = PJ2
101     CONTINUE
102
103     DPJ = NLAT*(PJ0-X*PJ1)/(1.D0-X*X)
104
105     X = X - PJ1/DPJ
106
107     * check the criterion for convergence
108     IF(ABS(X-XPREV) .LE. EPS) GO TO 1
109     IF(ITR .EQ. ITRMAX) GO TO 999
110
111     XPREV = X
112     CONTINUE
113     CONTINUE
114     * the criterion for convergence is fulfilled
115     * determine DCCLT, DCOLAT
116     DCCLT (L) = X
117     DCOLAT(L) = ACOS(X)*RADINV
118
119     * computation of the Gaussian weight
120     DGW(L) = 2.D0 * (1.D0-X*X) / (NLAT*NLAT*PJ0*PJ0)
121     CONTINUE
122     *-----
123
124     * determine the southern hemisphere values by symmetry
125     DO 40 L=1,NLAH
126     DCOLAT(NLAT-L+1) = - DCOLAT(L) + 180.D0
127     DCCLT (NLAT-L+1) = - DCCLT (L)
128     DGW (NLAT-L+1) = DGW (L)
129     CONTINUE
130
131     * print out -----
132     WRITE(6,600)
133

```

```

133 600 FORMAT(25X, 'COS(COLATITUDE)', 25X, 'COLATITUDE( DEG)',
134 + 25X, 'GAUSSIAN WEIGHT' )
135 WRITE(6,610) (DCCLT(L), DCOLAT(L), DGW(L), L=1, NIAT)
136 FORMAT( 5X, F35.30, 5X, F35.30, 5X, F35.30)
137
138 SUM = 0.D0
139 DO 50 L=1, NIAT
140 SUM = SUM + DGW(L)
141 CONTINUE
142
143 WRITE(6,620) SUM
144 FORMAT(//10X, 'SUM OF WEIGHTS = ', F40.35)
145
146 RETURN
147
148 -----
149 * not converged
150 CONTINUE
151 WRITE(6,699) L
152 FORMAT(10X, 'COMPUTATION DID NOT CONVERGE AT SUBROUTINE GAUSS' /
153 + 10X, 'L = ', I3)
154 WRITE(6,698) X, XPREV
155 FORMAT(10X, 'X = ', F36.30, 5X, 'XPREV = ', F36.30)
156 STOP 999
157
158 END
159 *****
160 SUBROUTINE LGNDR( DCCLT, GW, PMN, DPMN )
161 *
162 LGNDR generates the values of associated Legendre functions
163 * and their derivatives for given Gaussian latitude.
164 *
165 * On entry:
166 * DCCLT - cos(Gaussian colatitude)
167 * GW - Gaussian weights
168 *
169 * On exit:
170 * PMN - normalized Legendre functions
171 * DPMN - d(PMN)/d(COSCLT)
172 *
173 * for each Gaussian latitude
174 *****
175 IMPLICIT REAL* 8(A-H,O-Z)
176
177 * transform resolution parameters
178 * grid resolution
179 PARAMETER ( NIION= 128, NIAT= 64, NIOH=NIION/2, NIAH=(NIAT+1)/2 )
180 * spectral resolution
181 PARAMETER ( MT= 42 )
182
183 DIMENSION DCCLT(NIAT), GW(NIAT)
184 DIMENSION DP (0:MT,0:MT+1), DDP (0:MT,0:MT)
185 DIMENSION PMN(NIAT,0:MT), DPMN(NIAT,0:MT,0:MT)
186 -----
187 DO 10 J=1, NIAT
188 CALL LGNDR1( DCCLT(J), DP, DDP )
189
190 DO 20 M=0, MT
191 DO 20 N=M, MT
192 PMN (J,N,M) = DP (M,N)
193 DPMN(J,N,M) = DDP(M,N) / (DCCLT(J)*DCCLT(J)-1.D0)
194 CONTINUE
195 CONTINUE
196
197 * print out(including some checking routines)
198 WRITE(6, '(1H1)')

```

```

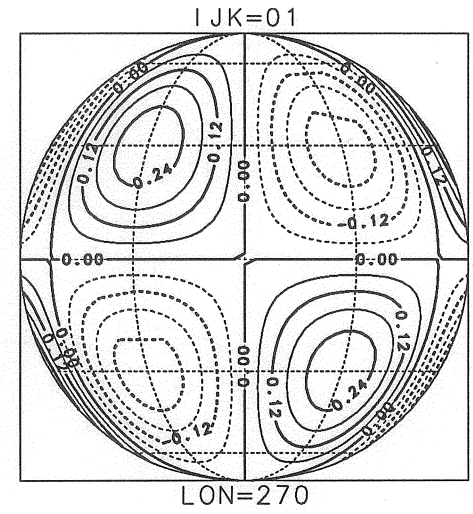
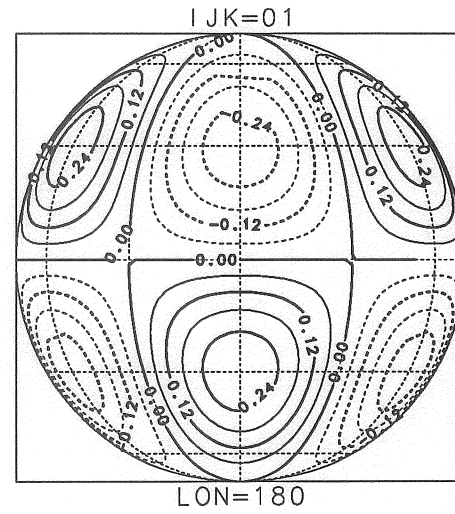
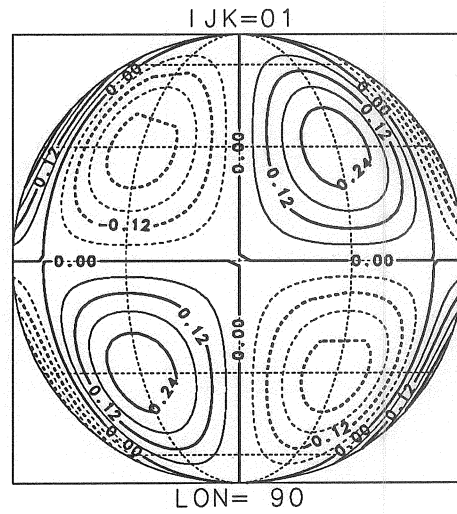
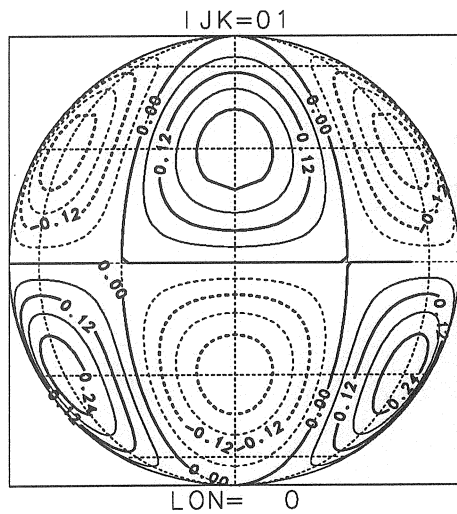
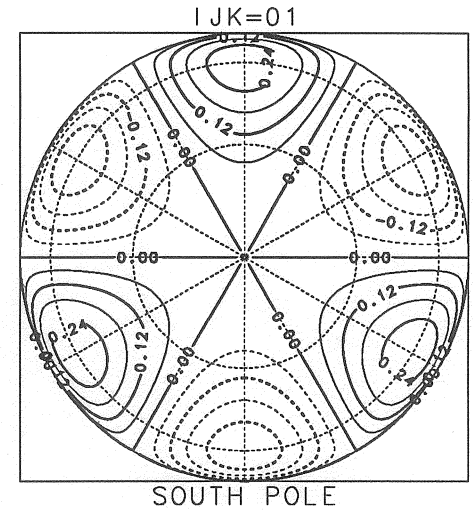
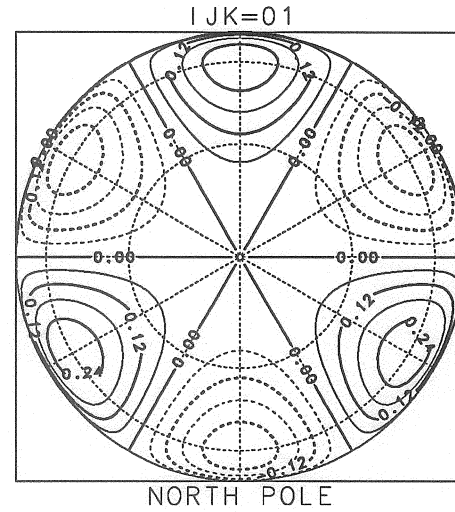
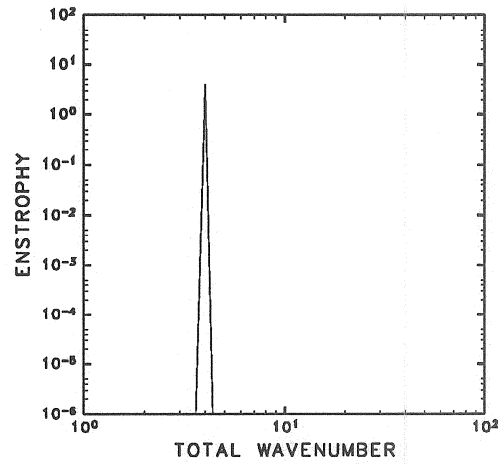
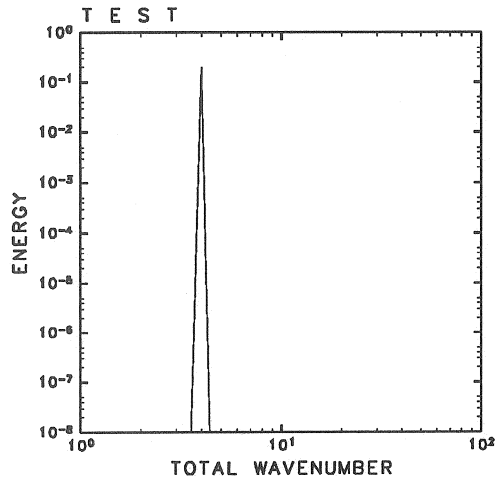
199
200      DO 30 M=0,MT
201      DO 30 N=M,MT
202          SUMP = 0.D0
203          SUMDP = 0.D0
204      204
205      DO 40 J=1,NLAT
206          SUMP = SUMP      +  PMN(J,N,M) *  PMN(J,N,M) *GW(J)
207          SUMDP = SUMDP  +  DPMN(J,N,M) *DPMN(J,N,M) *GW(J)
208      208      CONTINUE
209
210          WRITE(6,'(//)')
211          DO 50 J=1,NLAT
212              WRITE(6,610) J, M, N, PMN(J,N,M), DPMN(J,N,M)
213              FORMAT(' J=', I3, ' (M,N)=(', I3, ', ', I3, ') PMN = ',
214                  +  F13.8, ' DPMN = ', F13.8 )
215          50      CONTINUE
216
217          WRITE(6,620) SUMP, SUMDP
218          FORMAT(1X, 'SUMP = ', F36.30, ' SUMDP = ', F40.30 )
219      620      CONTINUE
220
221      RETURN
222      END
223      *****
224      SUBROUTINE LGNDR1( X, P, DP )
225      *
226      * LGNDR1 generates the values of associated Legendre functions
227      * and their derivatives for a given latitude.
228      *
229      * On entry:
230      * X - cos(Gaussian colatitude)
231      *
232      * On exit:
233      * P - normalized Legendre functions
234      * DP - (X**2-1) * dp/dx
235      * for a given Gaussian latitude
236      *****
237
238      IMPLICIT REAL* 8(A-H,O-Z)
239
240      * transform resolution parameters
241      * grid resolution
242      PARAMETER ( NION= 128, NLAT= 64, NIOH=NION/2, NLAH=(NLAT+1)/2 )
243      * spectral resolution
244      PARAMETER ( MT= 42 )
245
246      DIMENSION P(0:MT,0:MT+1), DP(0:MT,0:MT)
247      247 -----
248      SIA = SQRT( 1.D0 - X*X )
249
250      * m=0
251      P (0,0) = 1.D0
252      P (0,1) = SQRT( 3.D0 ) * X
253      DP(0,0) = 0.D0
254
255      E1 = 1.D0 / SQRT( 3.D0 )
256      DO 10 N=2,MT+1
257          E2 = SQRT( N*N / (4.D0*N*N - 1.D0) )
258      P (0,N) = (X*P(0,N-1) - E1*P(0,N-2)) / E2
259      DP(0,N-1) = (N-1.D0)*E2*P(0,N) - N*E1*P(0,N-2)
260      E1 = E2
261      CONTINUE
262      10
263      * m=1,2,...,MT
264      DO 20 M=1,MT

```

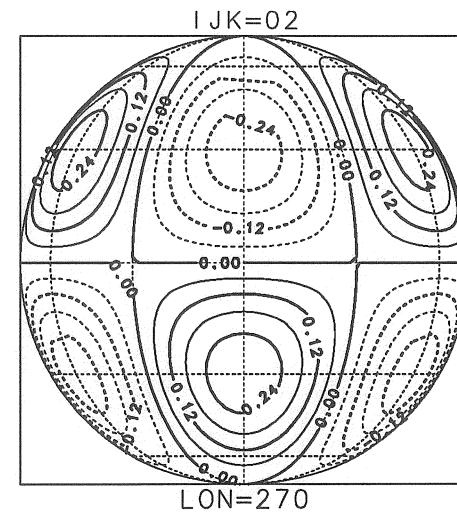
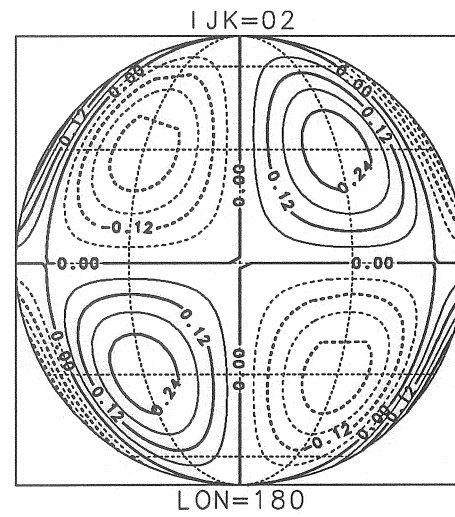
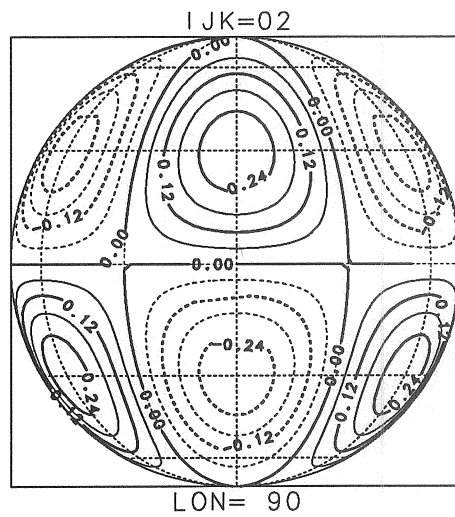
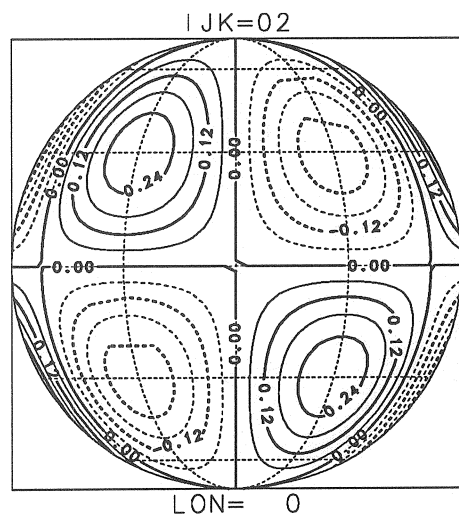
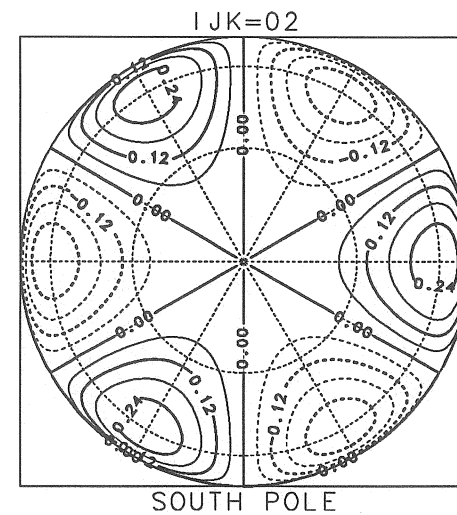
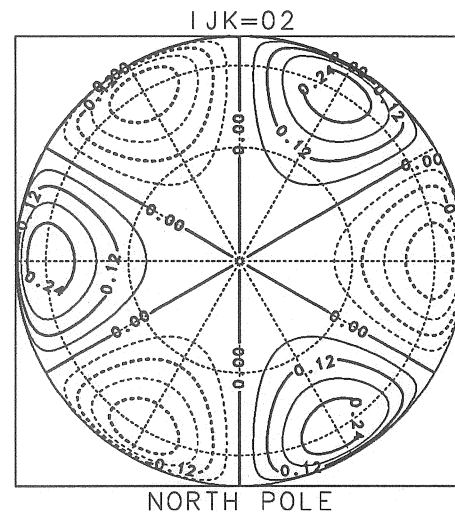
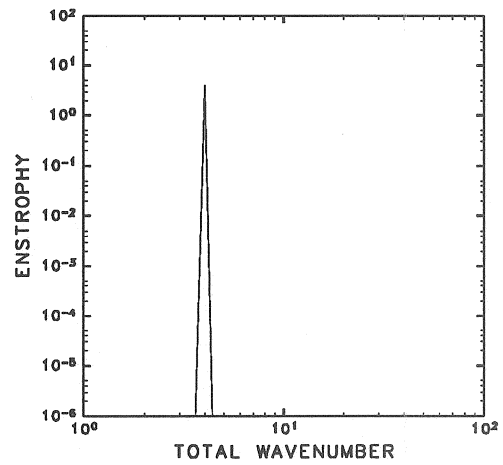
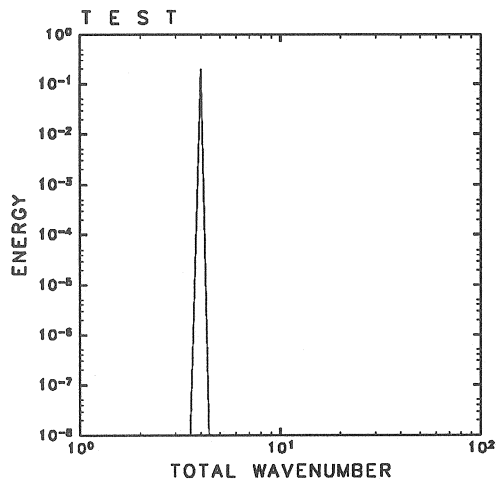
```

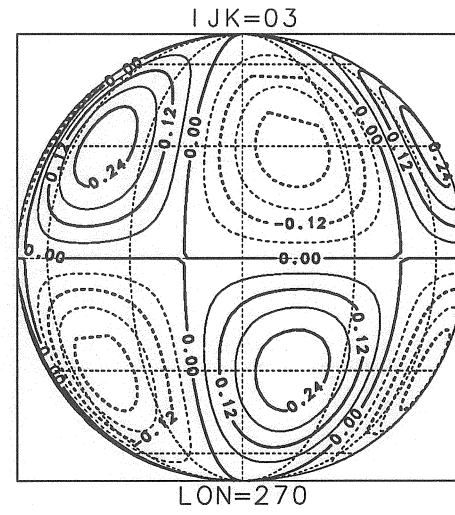
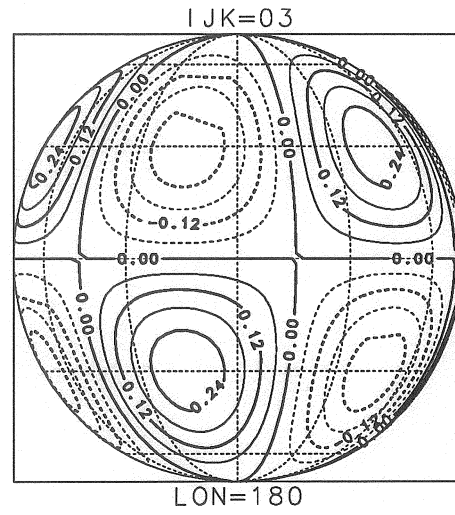
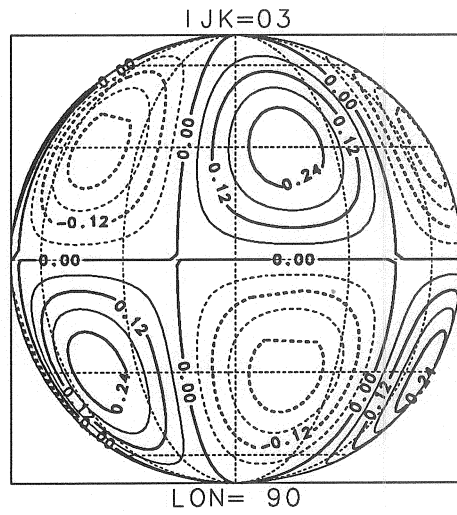
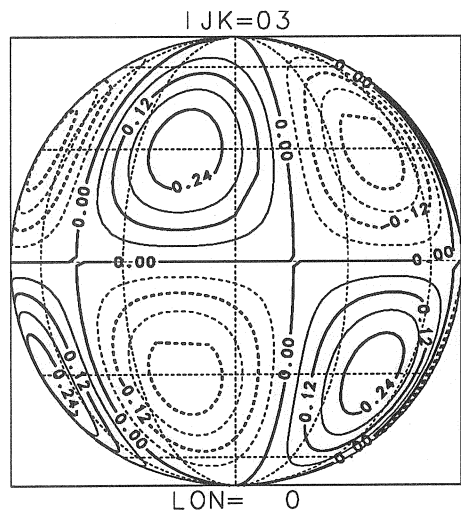
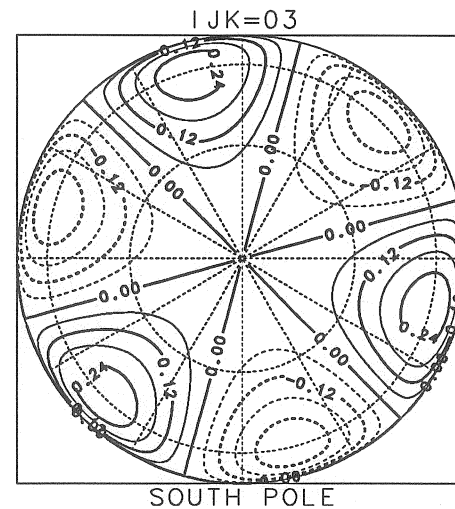
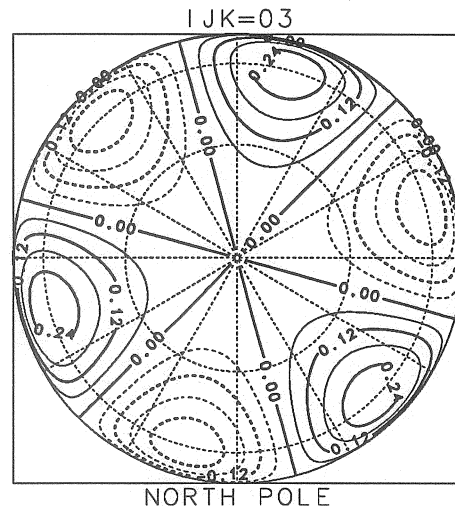
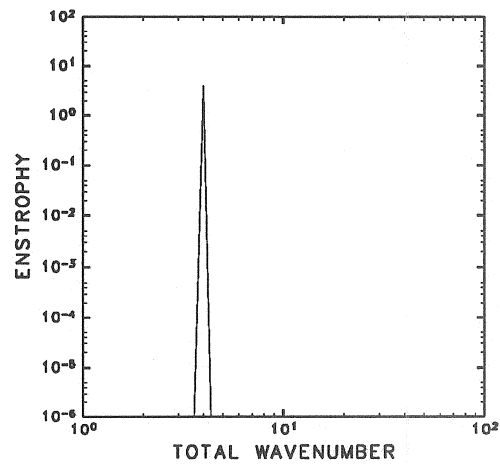
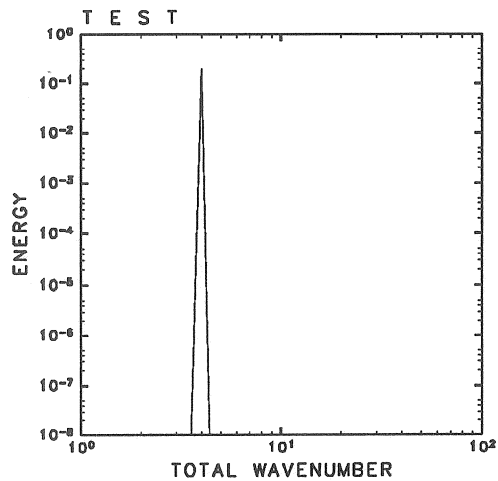
265 P(M,M) = SQRT( 2.D0*M+1.D0)/(2.D0*M) * SIA * P(M-1,M-1)
266 P(M,M+1) = SQRT( 2.D0*M+3.D0) * X * P(M,M)
267
268 E1 = 1.D0 / SQRT( 2.D0*M+3.D0)
269 DP(M,M) = M*E1*P(M,M+1)
270
271 DO 30 N=M+2,MT+1
272 E2 = SQRT( (N*N - M*M) / (4.D0*N*N - 1.D0) )
273 P(M,N) = (X*P(M,N-1) - E1*P(M,N-2)) / E2
274 DP(M,N-1) = (N-1.D0)*E2*P(M,N) - N*E1*P(M,N-2)
275 E1 = E2
276 CONTINUE
277 CONTINUE
278
279 RETURN
280 END
281
282
283

```



goff + f





```

1 *****
2 *
3 *      set an initial value for time-integration
4 *      assuming an initial energy spectrum
5 *
6 *****
7
8
9
10
11
12 * transform resolution parameters
13 * grid resolution
14 * PARAMETER ( NION= 256, NLAT= 128, NLOH=NION/2, NLAH=(NLAT+1)/2 )
15 * spectral resolution
16 * PARAMETER ( MT= 85, MT2=(MT+1)**2 )
17
18 DIMENSION ZP (0:MT,0:MT)
19 DIMENSION ENG(0:MT), ENS(0:MT)
20 DIMENSION RAM(MT2), RPH(MT2)
21 DOUBLE PRECISION RAND(MT2)
22 CHARACTER CWDATA*38, CW*35, CT*3
23
24 DATA CW/'/home/stupid05/yoden/turbsp/initia'/'/
25
26
27
28
29
30
31
32
33
34
35
36 * make radom numbers
37 CALL URAND1 ( MT2, RAND, IR )
38 DO 1 N=1,MT2
39   RAM(N) = RAND (N)
40   CONTINUE
41
42 CALL URAND1 ( MT2, RAND, IR )
43 DO 2 N=1,MT2
44   RPH(N) = RAND (N)
45   CONTINUE
46
47
48
49
50
51
52
53
54
55
56
57
58
59
60
61
62
63
64
65
66

```

```

*      set an initial value for time-integration
*      assuming an initial energy spectrum

```

```

PROGRAM GINIT
IMPLICIT COMPLEX (Z)

```

```

* transform resolution parameters
* grid resolution
* PARAMETER ( NION= 256, NLAT= 128, NLOH=NION/2, NLAH=(NLAT+1)/2 )
* spectral resolution
* PARAMETER ( MT= 85, MT2=(MT+1)**2 )

```

```

DIMENSION ZP (0:MT,0:MT)
DIMENSION ENG(0:MT), ENS(0:MT)
DIMENSION RAM(MT2), RPH(MT2)
DOUBLE PRECISION RAND(MT2)
CHARACTER CWDATA*38, CW*35, CT*3

```

```

DATA CW/'/home/stupid05/yoden/turbsp/initia'/'/

```

```

PI = 4*ATAN(1.0)
IR = 0

```

```

* parameters for initial data
E0 = 1.0
B = 0.5

```

```

DO 10 IJK=1,10

```

```

* make radom numbers
CALL URAND1 ( MT2, RAND, IR )
DO 1 N=1,MT2
  RAM(N) = RAND (N)
  CONTINUE

```

```

CALL URAND1 ( MT2, RAND, IR )
DO 2 N=1,MT2
  RPH(N) = RAND (N)
  CONTINUE

```

```

SEN = 0.0
DO 20 N=0,MT
  SEN = SEN + EXP (-B*N) *N*N*N*N*N*N
CONTINUE

```

```

A = E0/SEN

```

```

* make initial data
J = 0
K = 0

```

```

DO 30 N=0,MT

```

```

ENG(N) = A*EXP (-B*N) *N*N*N*N*N*N

```

```

*
  FOR M=0
    J = J + 1
    SAM = RAM(J)

```

```

DO 40 M=1,N

```

```

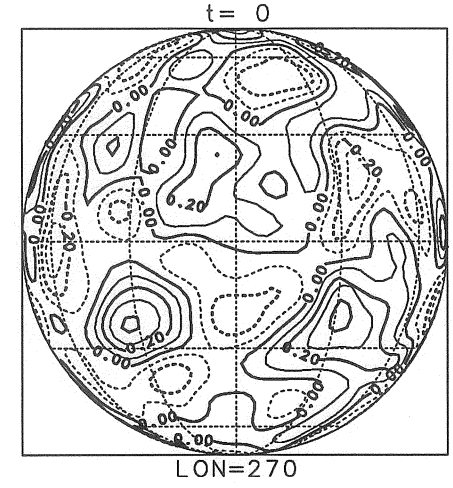
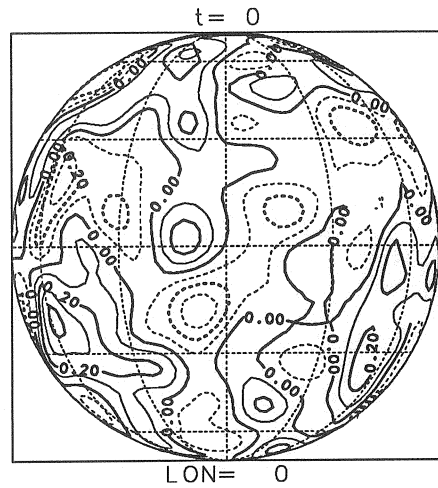
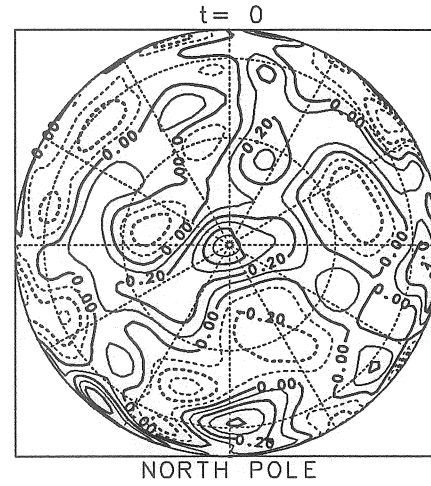
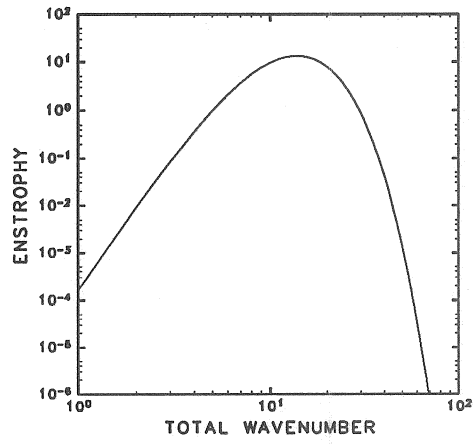
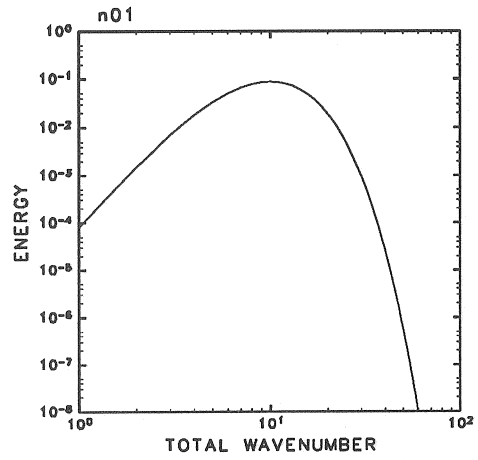
67      J = J + 1
68      SAM = SAM + RAM(J)*2
69      CONTINUE
70
71      DO 50 M=0,N
72          K = K + 1
73          PHA = RPH(K)*2*PI
74          AMP = RAM(K)/SAM
75          IF(N.EQ.0) THEN
76              AMP = 0
77          ELSE
78              AMP = SQRT( AMP * 2*ENG(N) / (N**2+N) )
79          END IF
80
81          IF(M.EQ.0) THEN
82              ZP(N,M) = AMP
83          ELSE
84              ZP(N,M) = AMP * EXP( (0.,1.)*PHA )
85          END IF
86          CONTINUE
87      CONTINUE
88
89      * storage of the initial data on disk
90      CT = 'n??'
91      WRITE(CT(2:3), '(I2.2)') IJK
92      CWDATA = CW // CT
93
94      OPEN (1, FILE=CWDATA, FORM='UNFORMATTED')
95      WRITE(1) MT, NLAT, ZP
96      CLOSE(1)
97
98      * compute energy and enstrophy spectrum
99      DO 60 N=0,MT
100         ENG(N) = 0.5*N*(N+1)*ABS(ZP(N,0))**2
101         ENS(N) = 0.5*N*(N+1)*ABS(ZP(N,0))**2 *N*(N+1)
102     DO 60 M=1,N
103         ENG(N) = ENG(N) + N*(N+1)*ABS(ZP(N,M))**2
104         ENS(N) = ENS(N) + N*(N+1)*ABS(ZP(N,M))**2 *N*(N+1)
105     CONTINUE
106
107     * compute characteristic scales
108     TOENG = 0.0
109     TOENS = 0.0
110     DO 70 N=0,MT
111         TOENG = TOENG + ENG(N)
112         TOENS = TOENS + ENS(N)
113     CONTINUE
114
115     CVEI = SQRT( TOENG )
116     CIEN = SQRT( TOENG/TOENS )
117     CTIM = CIEN/CVEI
118
119     * output
120     WRITE(6,600) IJK, A, B
121     FORMAT(2X, '<<< INITIAL STATE >>>'/
122     5X, 'J =', I2.2, 5X, 'A =', E12.5, 5X, 'B =', F5.2)
123     WRITE(6,610) TOENG, TOENS, CVEI, CIEN
124     FORMAT(5X, 'TOTAL ENERGY =', E12.5, /
125     5X, 'TOTAL ENSTROPHY =', E12.5, /
126     5X, 'VELOCITY SCALE =', E12.5, /
127     5X, 'LENGTH SCALE =', E12.5, /)
128     CONTINUE
129
130     -----
131     STOP
132     END

```

```

133 *****
134 SUBROUTINE URAND1(N, X, IR)
135 *****
136 * UNIFORM RANDOM NUMBER GENERATOR (MIXED CONGRUENTIAL METHOD)
137 * PORTABLE BUT SLOW. THE PERIOD IS ONLY 1664501.
138 * PARAMETERS
139 * (1) N (I) THE NUMBER OF RANDOM NUMBERS TO BE GENERATED
140 * (INPUT)
141 * (2) X (D) UNIFORM RANDOM NUMBERS (OUTPUT)
142 * (3) IR (I) THE INITIAL SEED (INPUT)
143 * THE SEED FOR THE NEXT CALL (OUTPUT)
144 * COPYRIGHT: Y. OYANAGI, JUNE 30, 1989 V.1
145 *****
146 *
147 DOUBLE PRECISION X(N), INVM
148 PARAMETER (M = 1664501, LAMBDA = 1229, MU = 351750)
149 PARAMETER (INVM = 1.0D0 / M)
150 *PARAMETER CHECK
151 IF ( N .LE. 0) THEN
152 WRITE(6,*) '(SUBR.URAND1) PARAMETER ERROR. N = ', N
153 WRITE(6,*) ' RETURN WITH NO FURTHER CALCULATION.'
154 RETURN
155 END IF
156 IF ( IR .LT. 0 .OR. IR .GE. M) THEN
157 WRITE(6,*) '(SUBR.URAND1) WARNING. IR = ', IR
158 END IF
159 *MAIN LOOP
160 DO 10 I = 1, N
161 IR = MOD( LAMBDA * IR + MU, M)
162 X(I) = IR * INVM
163 CONTINUE
164 RETURN
165 END

```



NO.

Jacobian 計算:

$$\begin{aligned} J(u, \omega) &= \frac{\partial u}{\partial t} \frac{\partial \omega}{\partial u} - \frac{\partial u}{\partial u} \frac{\partial \omega}{\partial t} \\ &= \frac{\partial^2 u}{\partial t \partial u} (\omega) - \frac{\partial^2 u}{\partial u \partial t} (\omega) + \end{aligned}$$

K/L

計算 1

a weak non-linear system

支配方程式

wave: (2-10)

$$\frac{\partial \zeta'}{\partial t} + \frac{1}{a^2} J(\bar{\psi}, \zeta') + \frac{1}{a^2} J(\psi', \bar{\phi}) = F' \quad (C-1)$$

zonal: (2-15)

$$\frac{\partial \bar{\zeta}}{\partial t} + \frac{1}{a^2 \cos \phi} \frac{\partial}{\partial \phi} \left(\bar{\zeta}' \frac{\partial \psi'}{\partial \lambda} \right) = \bar{F} \quad (C-2)$$

$$\bar{\zeta}' = \Delta_{\lambda} \psi'$$

$$\bar{\zeta} = \frac{1}{a^2 \cos \phi} \frac{\partial}{\partial \phi} \left(\cos \phi \frac{\partial \bar{\psi}}{\partial \phi} \right)$$

$$\bar{\phi} = \bar{\zeta} + 2\Omega \sin \phi$$